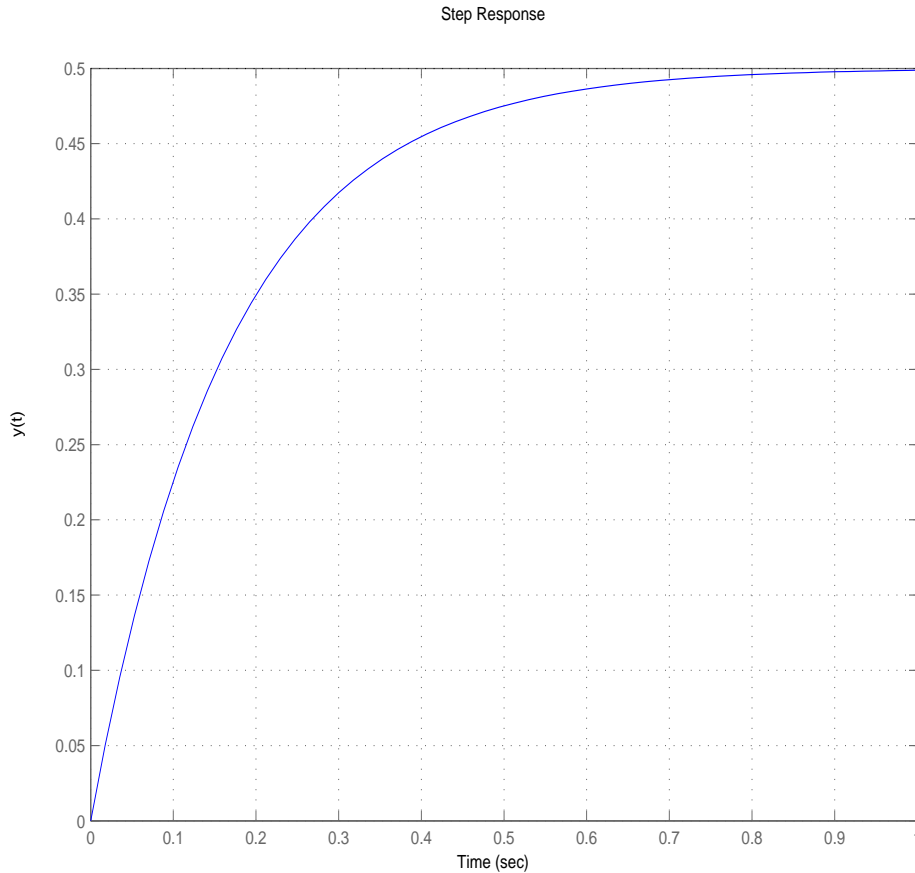


Due Tuesday, October 6

- The plot below shows the response,  $y(t)$ , of a first-order system,  $b/(s + a)$ , to a step input of height 3.



The purpose of this problem is to find the values of  $a$  and  $b$  from the step-response plot. Note that the equation for  $y(t)$  is

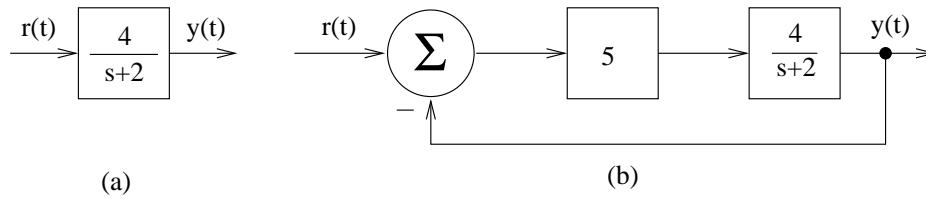
$$y(t) = \frac{3b}{a}(1 - e^{-at}).$$

The steady-state value of  $y(t)$ , call it  $y_{ss}$ , can be obtained from the graph and is given by the expression

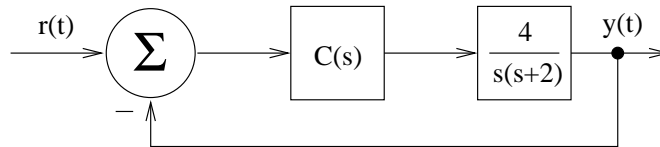
$$y_{ss} = \frac{3b}{a}.$$

Note that at time  $t = 1/a$  seconds, the expression  $1 - e^{-at}$  equals  $1 - e^{-1}$ , which equals 0.63. Thus, the time at which the response,  $y(t)$  crosses the value of  $0.63y_{ss}$  is equal to  $1/a$ . This allows the value of  $a$  to be determined from the plot.

2. Sketch (by hand) the unit step responses of the following systems. Label the steady-state values and the settling times on the graphs.



3. Problem 4.2 from the book.
4. Problem 4.4 (a) from the book. Find  $\zeta$  and  $\omega_n$  for the closed-loop system. Sketch (by hand) the unit step response.
5. Problem 4.14(a) from the book.
6. Consider the following control system:



- (a) Let  $C(s) = K$ . Find the value of  $K$  that results in the closed-loop system having a damping ratio of  $\zeta = 1.2$ . What are the closed-loop poles? What is the approximate settling time?
- (b) Now let  $C(s) = K(s + \beta)/(s + \alpha)$ . Find the values of  $K, \beta, \alpha$  so that the closed-loop system again has a damping ratio of  $\zeta = 1.2$  but has a settling time that is half of that found in part (a).