

## ELE 338 Electronics I

I. Review of Linear Circuit Theory

Tools for linear circuit analysis?

1. KVL  $\left| \sum_{\text{Mesh}} v_i = 0 \right|$
2. KCL  $\left| \sum_{\text{Node}} I_i = 0 \right|$
3. Device eq. (e.g. Ohm's Law  $V_R = R \cdot I_R$ )

Device  $v-i$  characteristics (time domain)

$$R = \frac{V_R}{I_R}$$

$$V_R = R \cdot I_R$$

$$I_R = \frac{1}{R} V_R$$

$$L = \frac{\Phi_L}{I_L} \quad \text{Flux}$$

$$V_L = \frac{d\Phi_L}{dt} = L \cdot \frac{dI_L}{dt}$$

$$\text{or } I_L = \frac{1}{L} \int V_L dt$$

$$C = \frac{Q_C}{V_C} \quad \text{charge}$$

$$I_C = \frac{dQ_C}{dt} = C \cdot \frac{dV_C}{dt}$$

$$\text{or } V_C = \frac{1}{C} \int I_C dt$$

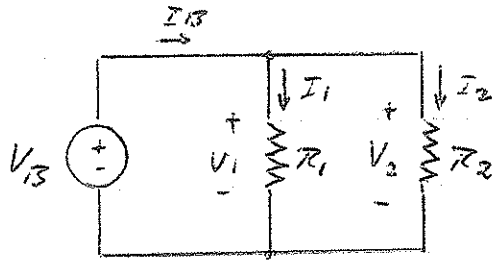
Laplace domain

$$V_L(s) = L \cdot I_L(s) \cdot s \quad \text{or} \quad I_L(s) = \frac{1}{sL} V_L(s)$$

$$I_C(s) = C \cdot V_C(s) \cdot s \quad \text{or} \quad V_C(s) = \frac{1}{sC} I_C(s)$$

Notes for sinusoidal signals  $s \rightarrow j\omega$

Example 1:



Determine the 2 voltages  $V_1$  and  $V_2$  and the 3 currents  $I_B$ ,  $I_1$  and  $I_2$  as a function of  $V_B$ ,  $R_1$  and  $R_2$

Solution:

Step 1: 5 unknowns  $\therefore$  5 eq. needed

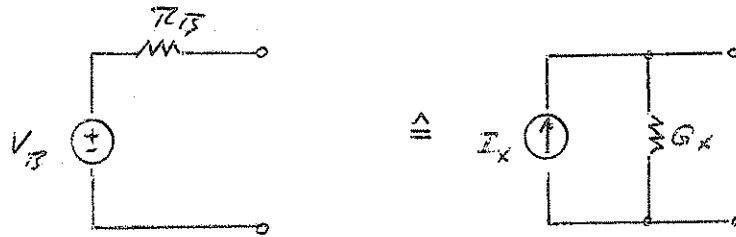
KVL 1: $V_B = V_1$
KVL 2: $V_B = V_2$
KCL: $I_B = I_1 + I_2$
Ohm's law 1: $V_1 = R_1 \cdot I_1$
Ohm's law 2: $V_2 = R_2 \cdot I_2$

Step 2: Solve for unknowns

$V_1 = V_B$
$V_2 = V_B$
$I_1 = V_B / R_1$
$I_2 = V_B / R_2$
$I_B = V_B / R_1 + V_B / R_2$

Note: Before you can write down any equations, you clearly have to define your variables (e.g. currents and voltages).

Example 2:



Determine  $Z_x$  and  $G_x$  so that the 2 circuits show identical terminal characteristics.

Solution:

We need 2 equations to determine the 2 unknowns  $I_x$  and  $G_x$ . To find them, we look at 2 specific load conditions of the 2 circuits and determine  $Z_x$  and  $G_x$  so that the resulting output voltages and currents become identical.

Condition 1:  $R_L \rightarrow \infty$  (open loop)

$$V_{o1} = V_B$$

$$V_{o2} = I_x / G_x$$

$$\text{Since } V_{o1} \equiv V_{o2} \quad \therefore | V_B = I_x / G_x | \quad (1)$$

Condition 2:  $R_L \rightarrow 0$  (short circuit)

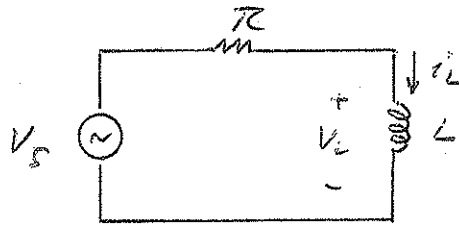
$$I_{s1} = V_B / R_B$$

$$I_{s2} = I_x$$

$$\text{Since } I_{s1} = I_{s2} \quad \therefore | I_x = V_B / R_B | \quad (2)$$

$$\therefore \left\| \begin{array}{l} I_x = V_B / R_B \\ G_x = 1 / R_B \end{array} \right\|$$

Example 3:



Determine  $i_L$  and  $V_L$  if  $V_S$  represents a sinusoidal voltage with a voltage swing of  $\hat{V}_S$ .  $V_S(t) = \hat{V}_S \sin(\omega t)$

Solution: (work in Laplace domain since input is sinusoidal)

$$\text{KVL: } V_S = i_L \cdot R + i_L \cdot s \cdot L$$

$$\text{Dev. eq: } V_L = i_L \cdot s \cdot L$$

$$\left| \begin{array}{l} i_L = \frac{V_S}{R + sL} \\ V_L = V_S \frac{sL}{R + sL} \end{array} \right|$$

$$i_L(j\omega) = \frac{V_S(j\omega)}{R + j\omega L}$$

$$V_L(j\omega) = V_S(j\omega) \frac{j\omega L}{R + j\omega L}$$

def. Voltage transfer function

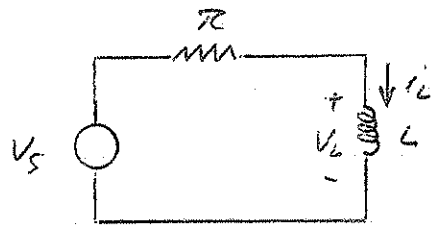
$$\left| T = \frac{V_L}{V_S} \right|$$

$$\therefore \left| T(j\omega) = \frac{V_L(j\omega)}{V_S(j\omega)} = \frac{j\omega L}{R + j\omega L} \right| \quad \text{complex function}$$

Bode plot: Magnitude  $|T(j\omega)| = \left| \frac{j\omega L}{R + j\omega L} \right|$

Phase  $\angle T(j\omega) = \phi_{\text{num}} - \phi_{\text{den}} = \frac{\pi}{2} - \tan^{-1}\left(\frac{\omega L}{R}\right)$

Example 4:



Determine  $i_L$  and  $V_L$  if  $V_s$  represents a step function that changes from 0 to  $V_{s0}$  at time  $t=0$ .

Solution:

A) Time domain equations

$$\begin{array}{l} \text{KVL: } | V_{s0} = i_L(t) \cdot R + L \cdot \frac{di_L(t)}{dt} | \quad t \geq 0 \\ \text{Dev. eq.: } | V_L(t) = L \cdot \frac{di_L(t)}{dt} | \quad t \geq 0 \end{array}$$

init. cond.  $V_L(t=0) = V_{s0}$   
 $i_L(t=0) = 0$

steady state:  $V_L(t \rightarrow \infty) = 0$   
 $i_L(t \rightarrow \infty) = V_{s0}/R$

Solution of 1st order diff. eq.

$$| i_L(t) = A + B e^{-t/\tau} | \quad \text{and} \quad | V_L(t) = -\frac{B L}{\tau} e^{-t/\tau} | \quad t \geq 0$$

$i_L(t=0) = 0 \quad \therefore B = -A$

KVL:  $\therefore \frac{A \cdot L}{\tau} = V_{s0}$

$i_L(t \rightarrow \infty) = V_{s0}/R \quad \therefore A = V_{s0}/R$

$$\therefore \left\| \begin{array}{l} i_L(t) = \frac{V_{s0}}{R} (1 - e^{-t/\tau}) \\ V_L(t) = \frac{V_{s0} L}{R \tau} e^{-t/\tau} \end{array} \right\| \quad \tau = \frac{L}{R} = L \cdot G \quad t \geq 0$$

13) Laplace domain equations

$$\text{KVL: } \left| V_{s0} \cdot \frac{1}{s} = i_L(s)R + sL i_L(s) \right| \quad (1) \quad \frac{1}{s} \text{ is unit step in}$$

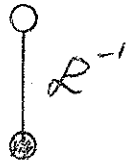
$$\text{Dev. eq.: } \left| V_L(s) = sL i_L(s) \right| \quad (2) \quad \text{Laplace domain}$$

$$\text{From (1) } \therefore \left| i_L(s) = \frac{V_{s0}}{L} \frac{1}{s(s + R/L)} \right|$$

$$= \frac{V_{s0}}{L} \frac{L}{R} \left[ \frac{1}{s} - \frac{1}{s + R/L} \right]$$

$$\therefore \left| i_L(s) = \frac{V_{s0}}{R} \left[ \frac{1}{s} - \frac{1}{s + R/L} \right] \right|$$

$$\left| V_L(s) = V_{s0} \frac{1}{s + R/L} \right|$$



$$\left| i_L(t) = \frac{V_{s0}}{R} u(t) \left[ 1 - e^{-\frac{t \cdot R}{L}} \right] \right| \quad \text{where } u(t) \text{ is the}$$

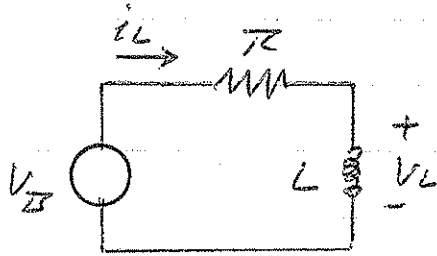
$$\left| V_L(t) = V_{s0} u(t) e^{-\frac{t \cdot R}{L}} \right| \quad \text{unit step function}$$

or

$$i_L(t) = \begin{cases} \frac{V_{s0}}{R} \left[ 1 - e^{-\frac{t \cdot R}{L}} \right] & \text{for } t \geq 0 \\ 0 & \text{else} \end{cases}$$

$$V_L(t) = \begin{cases} V_{s0} e^{-\frac{t \cdot R}{L}} & \text{for } t \geq 0 \\ 0 & \text{else} \end{cases}$$

## Step Response of RL Circuit



where

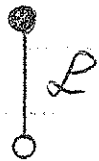
$$V_B(t) = V_{B0} \cdot u(t)$$

$u(t)$ : unit step function

2 unknowns  $\therefore$  2 equations needed

$$\text{KVL: } \left| \begin{array}{l} V_B(t) = i_L(t) R + V_L(t) \end{array} \right| \quad (1) \quad \text{where } V_B(t) = V_{B0} \cdot u(t)$$

$$\text{Dev.: } \left| \begin{array}{l} V_L(t) = L \cdot \frac{di_L}{dt} \end{array} \right| \quad (2)$$



$$\left| \begin{array}{l} V_B(s) = i_L(s) R + V_L(s) \end{array} \right| \quad (3) \quad \text{where } V_B(s) = V_{B0} \cdot \frac{1}{s}$$

$$\left| \begin{array}{l} V_L(s) = L \cdot s i_L(s) \end{array} \right| \quad (4)$$

Solving for  $i_L$  and  $V_L$  yields

$$\left\| \begin{array}{l} i_L(s) = V_B(s) \frac{1}{R + sL} = V_{B0} \cdot \frac{1}{s} \frac{1/L}{(R/L + s)} \end{array} \right\| \quad (5)$$

$$\left\| \begin{array}{l} V_L(s) = V_B(s) \frac{sL}{R + sL} = V_{B0} \cdot \frac{1}{s} \frac{s}{(R/L + s)} \end{array} \right\| \quad (6)$$

(5) and (6) can be rewritten as

$$\left\| \begin{aligned} \tilde{i}_L(s) &= \frac{V_{B0}}{R} \left[ \frac{1}{s} - \frac{1}{(\pi/L + s)} \right] \end{aligned} \right\| \quad (7)$$

$$\left\| \begin{aligned} \tilde{V}_L(s) &= V_{B0} \frac{1}{(\pi/L + s)} \end{aligned} \right\| \quad (8)$$

$$\mathcal{L}^{-1}$$

$$\left\| \begin{aligned} i_L(t) &= \frac{V_{B0}}{R} u(t) \left[ 1 - e^{-t \frac{\pi}{L}} \right] \end{aligned} \right\| \quad (9)$$

$$\left\| \begin{aligned} V_L(t) &= V_{B0} u(t) e^{-t \frac{\pi}{L}} \end{aligned} \right\| \quad (10)$$

Graphical Solution (TTL Step Response)

