

Selected Approaches to Estimation of Signal Phase

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- Let g_n be a sequence of complex values defined by

$$g_n = A_n e^{j\Phi_n}$$

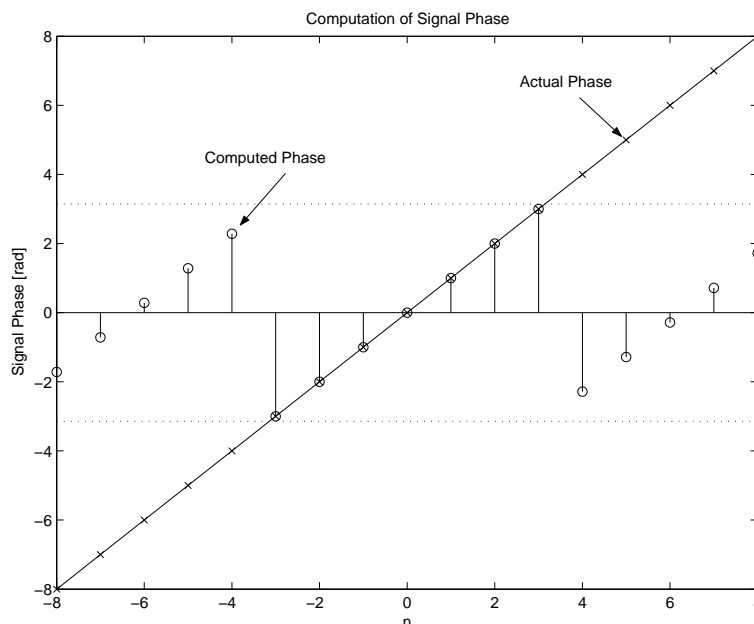
- We want to find the phase Φ_n (the argument of the exponent)

$$\Phi_n = \arg(g_n)$$

- Determination of Φ_n requires the computation of the inverse tangent

$$\hat{\Phi}_n = \tan^{-1} \left(\frac{\text{Im}\{g_n\}}{\text{Re}\{g_n\}} \right)$$

- The inverse tangent function is a many-to-one function. All values of Φ_n outside the interval $(-\pi, \pi)$ are mapped back into this interval.



- Technique for phase unwrapping:
 1. **Search** for jumps $> \pi$
 2. **Correct** jumps by adding a factor of $\pm 2\pi$ to all subsequent terms in the sequence

- Φ_n must obey

$$\Phi_n - \Phi_{n-1} < \pi \quad \text{for all } n$$

otherwise unwrapping is useless

1. **Phase tracking:** Φ_n can be tracked using a PLL, Least Mean Squares (LMS), moments of time-frequency distribution (TFDs), or by other means.
2. **Polynomial model** for Φ_n can be assumed

$$\Phi_n = a_0 + \cdots + a_p n^p$$

3. Combine both: Compute time localized phase polynomial, shift, repeat

In this investigation analysis is restricted to item 2. We will examine the cases of linear phase ($p = 1$), and quadratic phase ($p = 2$)

Phase Polynomial: $\Phi_n = 2\pi fn + \phi$

- Signal model x_n is complex exponential corrupted by complex white Gaussian noise z_n with variance σ^2

$$x_n = Ae^{j(2\pi fn + \phi)} + z_n$$

- Goal is to estimate the parameters of Φ_n , i.e. f and ϕ

- The MLE of f is given by

$$\hat{f} = \arg \max_f \frac{1}{N} \left| \sum_{n=0}^{N-1} x_n e^{-j2\pi f n} \right|^2$$

This is the value of f that maximizes the periodogram

- The MLE of ϕ

$$\hat{\phi} = \tan^{-1} \left[\frac{\text{Im} \left(\sum_{n=0}^{N-1} x_n e^{-j2\pi \hat{f} n} \right)}{\text{Re} \left(\sum_{n=0}^{N-1} x_n e^{-j2\pi \hat{f} n} \right)} \right]$$

The MLE of f is typically implemented in two steps

1. **Coarse Grid Search:** The periodogram is computed at discrete values using the FFT
2. **Fine Determination** of peak location: Using maxima from last step, can use a fine grid search, Newton's method, or interpolation.

*Some Suboptimal
But Computationally Efficient Methods*

Start with an approximation:

- Recall original model:

$$x_n = A e^{j(2\pi f n + \phi)} + z_n$$

where z_n is complex Gaussian noise with variance σ^2

- The following approximation can be made at high SNR:

$$x_n \approx A e^{j(2\pi f n + \phi + w_n)}$$

where w_n is real white Gaussian noise with variance $\sigma^2/2A^2$

- Note that if we can get hold of the phase, we have the linear model

$$\Phi_n = 2\pi fn + \phi + w_n$$

- This leads to one method for determining f and ϕ
 1. Find the phase using \tan^{-1} , then perform unwrapping
 2. Use least squares to find the unknown parameters.

- Note that if we can get hold of the differenced phase, we have

$$\begin{aligned}\Delta\Phi_n &= \Phi_{n+1} - \Phi_n \\ &= 2\pi f + \Delta w_n\end{aligned}$$

- Differenced phase is linear function of f , embedded in *colored* Gaussian noise
- $\Delta\Phi_n$ can be computed by $\angle x_n^* x_{n+1}$

- MLE solution for f using $\Delta\Phi_n$ is

$$\hat{f} = \frac{1}{2\pi} \sum_{n=n_0}^{n_0+N-2} h_n \left(\angle x_n^* x_{n+1} \right)$$

- Solution is statistically identical to previous approach, but is more computationally efficient.

Simulations are for $f = 0.05$ and $f = 0.35$

