

a)  $p_{S_3}(x) = \int_{-1}^{x+\frac{1}{2}} p_{S_2}(u) \cdot 1 du \quad -\frac{3}{2} \leq x \leq -\frac{1}{2}$

 $= \frac{1}{2} x^2 + \frac{3}{2} x + \frac{9}{8}$ 

b)  $p_{S_3}(x) = \int_{x-\frac{1}{2}}^{x+\frac{1}{2}} p_{S_2}(u) \cdot 1 du \quad -\frac{1}{2} \leq x \leq \frac{1}{2}$

 $= -x^2 + \frac{3}{4}$ 

c)  $p_{S_3}(x) = \int_{x-\frac{1}{2}}^1 p_{S_2}(u) \cdot 1 du \quad \frac{1}{2} < x \leq \frac{3}{2}$

 $= \frac{1}{2} x^2 - \frac{3}{2} x + \frac{9}{8}$ 

d)  $= 0 \quad \text{otherwise}$

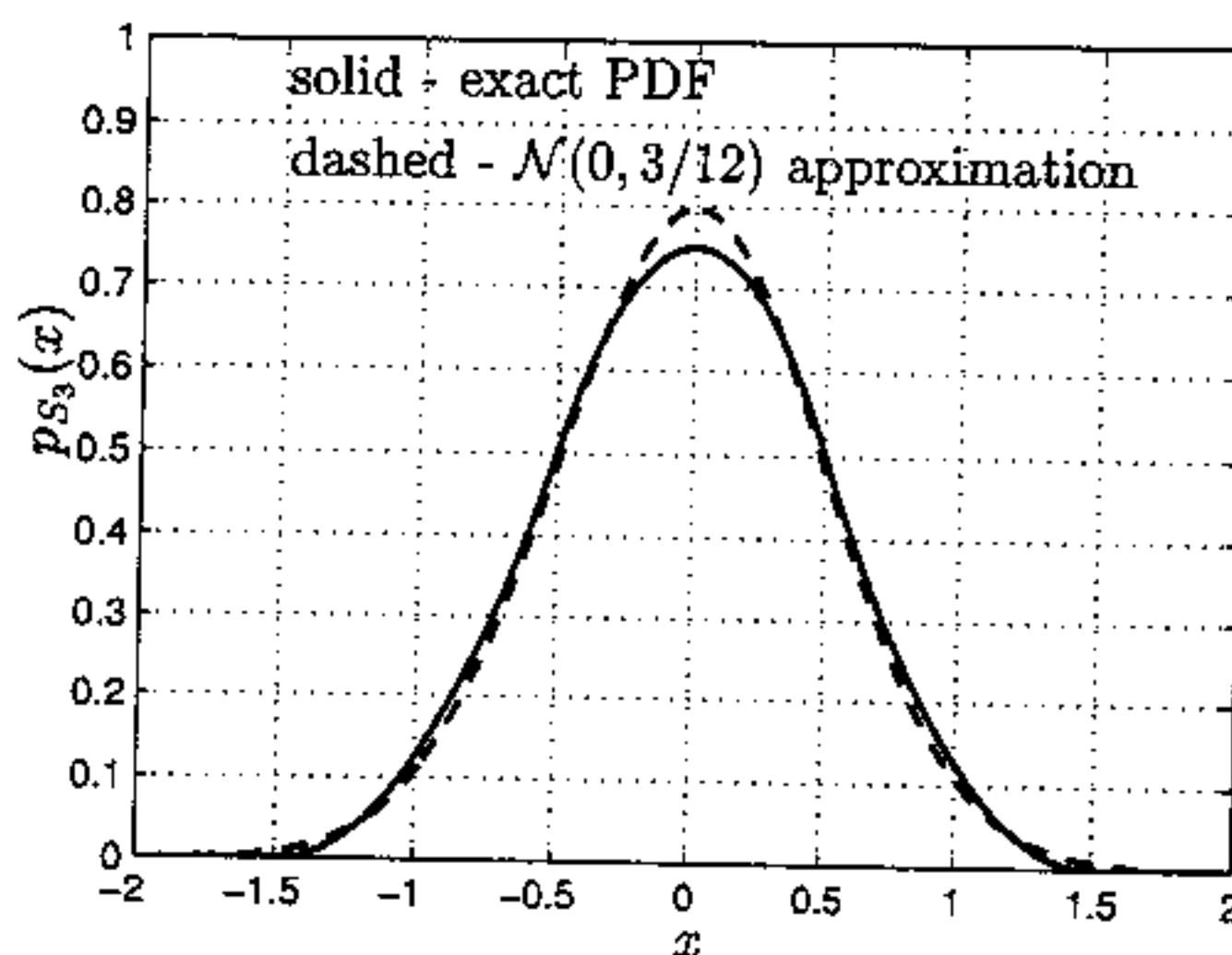


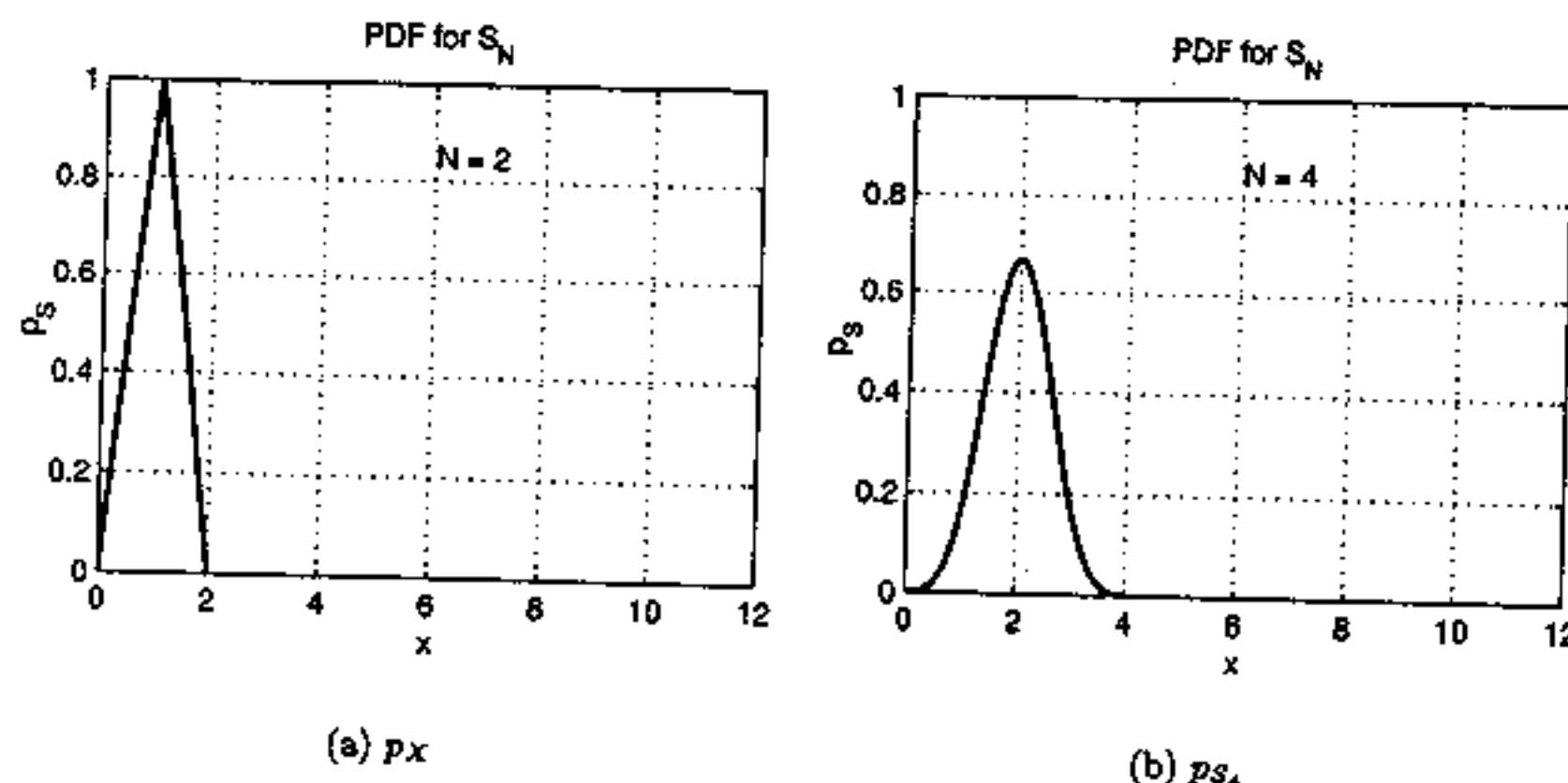
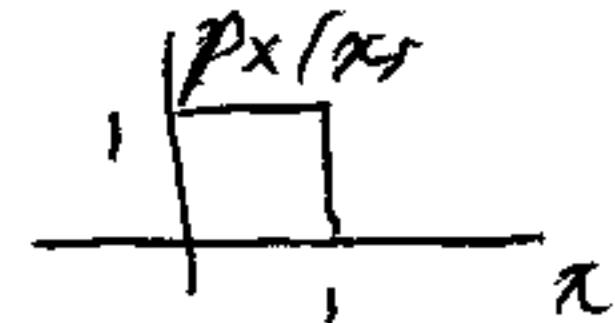
Figure 15.6: PDF for sum of 3 IID  $\mathcal{U}(-1/2, 1/2)$  random variables and Gaussian approximation.

NOTE:  $E[S_3] = E\left(\sum_{i=1}^3 X_i\right) = 0 \quad X_i \sim U\left(-\frac{1}{2}, \frac{1}{2}\right)$   
 $\text{VAR}(S_3) = \text{VAR}\left(\sum_{i=1}^3 X_i\right) = 3 \text{ VAR}(X_i) = \frac{3}{12}$

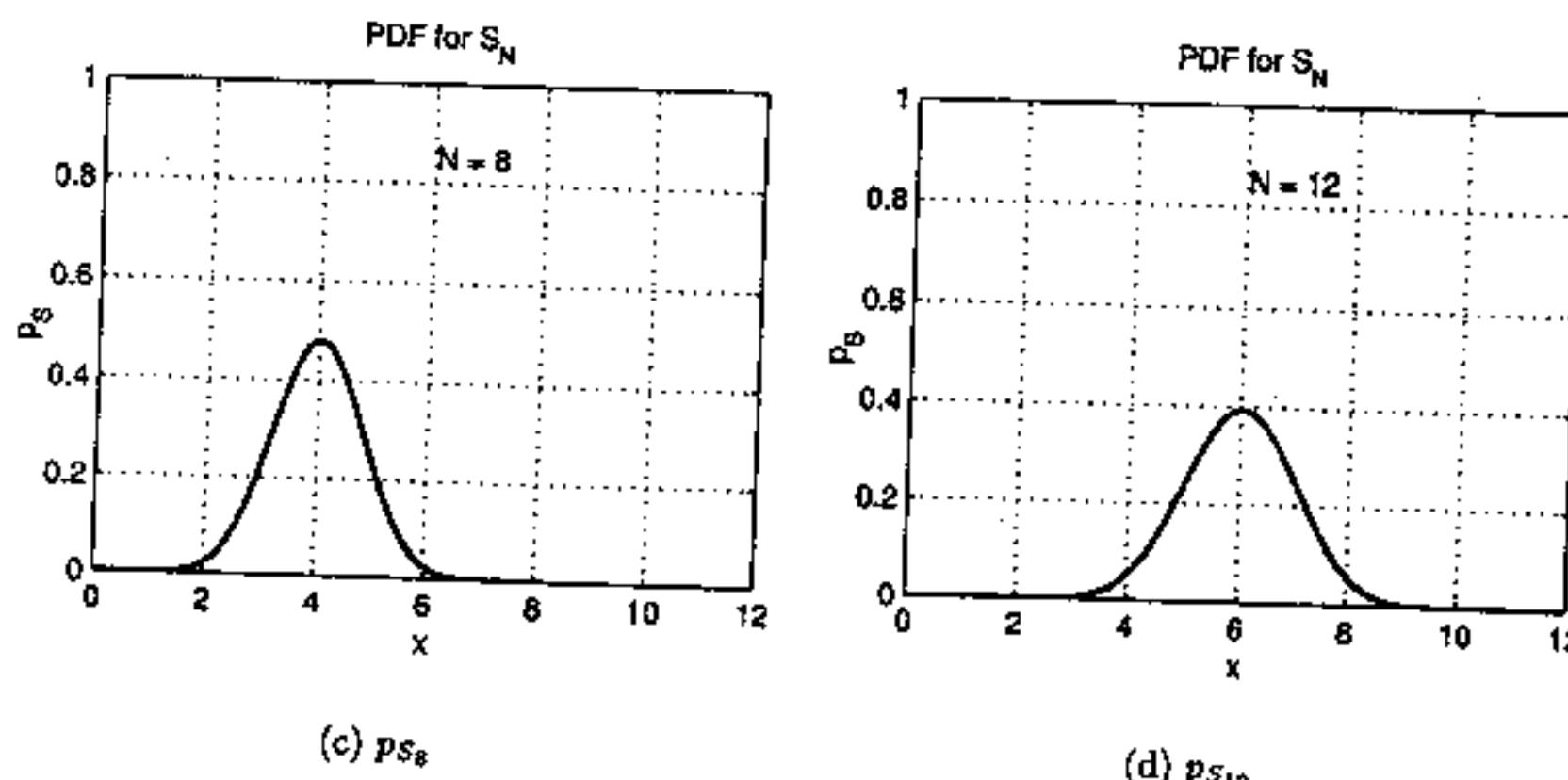
GAUSSIAN APPROXIMATION VERY GOOD  
NEAR  $x = 0$ . HOW ABOUT FOR  $x > 2$ ?

EXAMPLE :  $S_N = \sum_{i=1}^N X_i$   $X_i \sim N(0, 1)$   
IID

USING `clt-demo.m` (APPENDIX 15A) FOR  
REPEATED CONVOLUTION OF



DOES  $p_{S_N}$   
CONVERGE TO  
ANYTHING AS  
 $N \rightarrow \infty$ ?



NOTE :

$$\begin{aligned} E[S_N] &= E\left[\sum_{i=1}^N X_i\right] \\ &= \sum_{i=1}^N E[X_i] \\ &= N E[X] \\ &= N/2 \end{aligned}$$

Figure 15.7: PDF of sum of  $N$  IID  $U(0, 1)$  random variables. The plots were obtained using `clt-demo.m` listed in Appendix 15A.

ALSO  $\text{VAR}(S_N) = N \text{VAR}(X) = N/12$

MUST SOMEHOW NORMALIZE TO TALK ABOUT CONVERGENCE.

SIMILAR TO FOLLOWING:

$$\bar{D}_N = \frac{1}{N} \sum_{n=1}^N n = \frac{\frac{N}{2}(N+1)}{N} \rightarrow \infty \text{ AS } N \rightarrow \infty$$

OR AVERAGE OF FIRST  $N$  POSITIVE INTEGERS  
 $\rightarrow \infty$  AS  $N$  GETS LARGE. BUT WE WOULD  
 LIKE TO SAY THAT THIS AVERAGE  $\approx N/2$ .

EXAMINE  $\frac{\bar{D}_N}{N} = \frac{\frac{N}{2}(N+1)}{N^2} \rightarrow \frac{1}{2}$  AS  $N \rightarrow \infty$

OR  $\frac{\bar{D}_N}{N} \approx \frac{1}{2} \Rightarrow \bar{D}_N \approx N/2$

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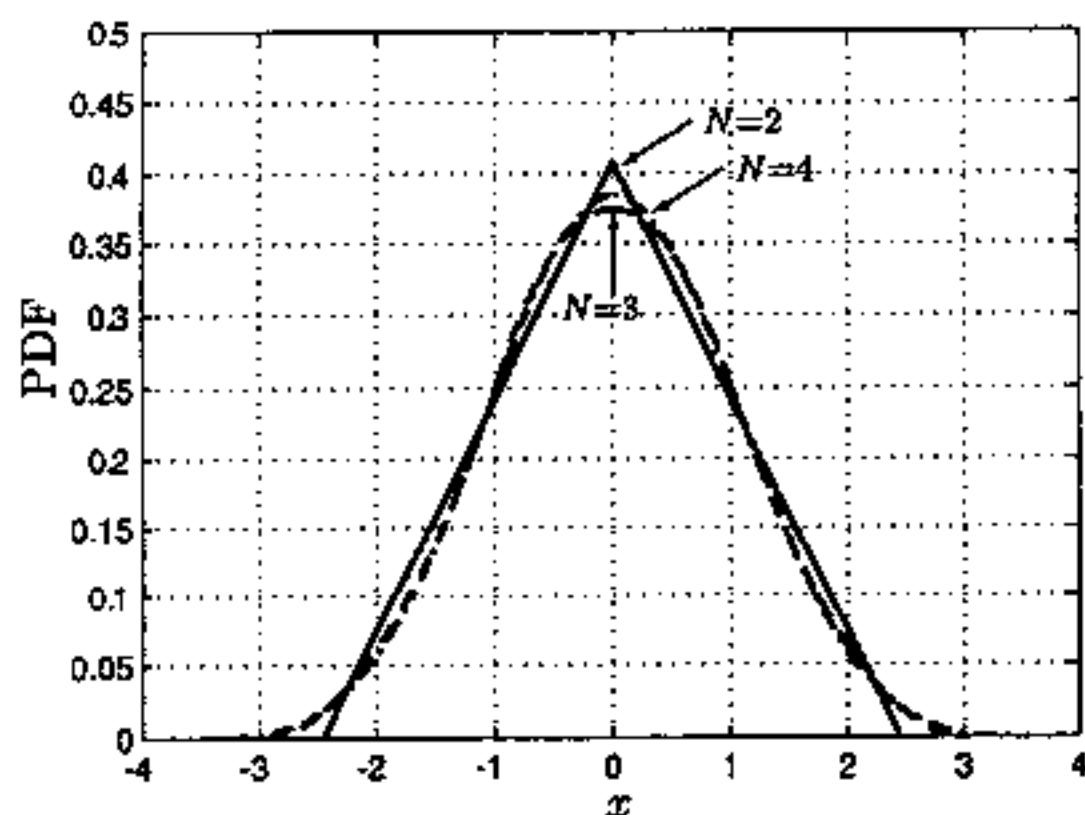
TO NORMALIZE  $S_N$  WE FORM STANDARDIZED  
 $S_N$  / RECALL STANDARD NORMAL HAD  
 $X \sim N(0, 1)$  OR  $E[X] = 0$ ,  $\text{VAR}(X) = 1$ .  
 SAME HERE!

$$Z_N = \frac{S_N - E(S_N)}{\sqrt{\text{VAR}(S_N)}}$$

HAS MEAN = 0, VARIANCE = 1 WHY?

$$Z_N = \frac{S_N - N E[x]}{\sqrt{N \text{VAR}(x)}} \quad \begin{array}{l} \text{WELL DEFINED} \\ \text{EVEN AS } N \rightarrow \infty \end{array}$$

FINALLY CENTRAL LIMIT THEOREM (CLT)  
 SAYS THAT AS  $N \rightarrow \infty$ ,  $Z_N \rightarrow N(0, 1)$



SAME EXAMPLE  
AS BEFORE -  
MUCH BETTER  
"BEHAVED"  
MATHEMATICALLY

Figure 15.8: PDF of standardized sum of  $N$  IID  $\mathcal{U}(0,1)$  random variables.

CLT : IF  $x_1, x_2, \dots, x_n$  ARE CONT. IID RVs EACH WITH MEAN  $E(x)$  AND VARIANCE  $VAR(x)$ , THEN AS  $N \rightarrow \infty$

$$\frac{\sum_{i=1}^N x_i - N E(x)}{\sqrt{N VAR(x)}} \rightarrow N(0, 1)$$

EXAMPLE :  $x_i \sim N(0, 1)$

EXAHINE PDF OF  $y = \sum_{i=1}^N x_i^2$   
AS  $N \rightarrow \infty$

TRUE PDF IS  $y \sim \chi_N^2$ . TO APPLY CLT  
NOTE :

- 1)  $x_1, x_2, \dots, x_n$  ARE IND  $\Rightarrow x_1^2, x_2^2, \dots, x_n^2$  ARE INDEPENDENT (CAN YOU JUSTIFY THIS? SEE PG. 200 IN BOOK)
- 2)  $x_1, x_2, \dots, x_n$  HAVE SAME PDF  
 $\Rightarrow x_1^2, x_2^2, \dots, x_n^2$  HAVE SAME PDF

AS PER CLT

$$\frac{\sum_{i=1}^N x_i^2 - N \mathbb{E}[x^2]}{\sqrt{N \text{Var}(x^2)}} \rightarrow N(0, 1)$$

BUT IF  $x \sim N(\mu, \sigma^2)$ ,

$$\mathbb{E}[x^2] = \text{Var}(x) + \underbrace{\mathbb{E}[x]^2}_{= \mu^2} = 1$$

$$\text{Var}(x^2) = \mathbb{E}[x^4] - \underbrace{\mathbb{E}[x^2]^2}_{= 1} = 2$$

CAN BE  
SHOWN TO = 3  
(TRY INTEGRATION)

$$Z_N = \frac{\sum_{i=1}^N x_i^2 - N}{\sqrt{2N}} \rightarrow N(0, 1)$$

$$Y_N = \sum_{i=1}^N x_i^2 = \sqrt{2N} Z_N + N \approx N(N, 2N) \rightarrow N(0, 1)$$

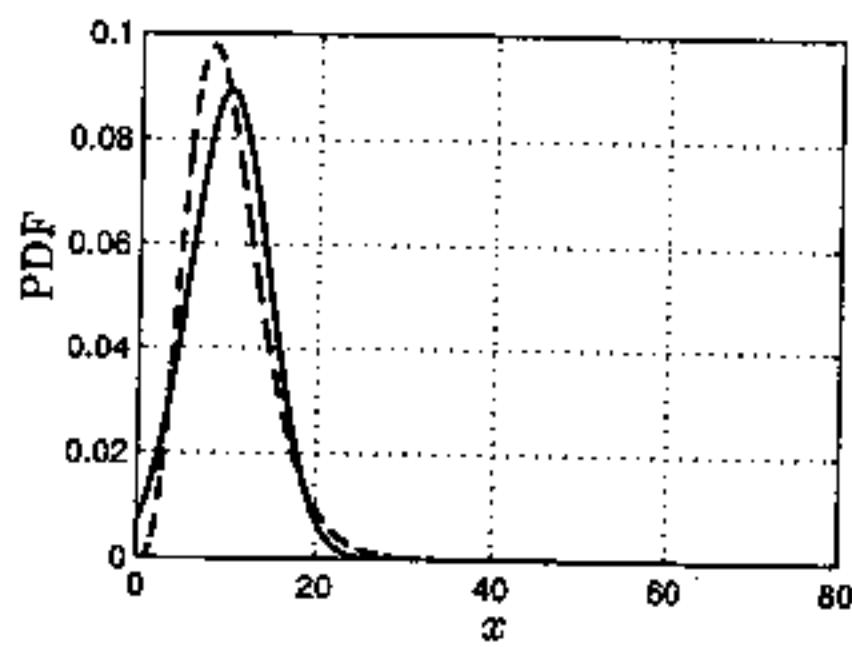
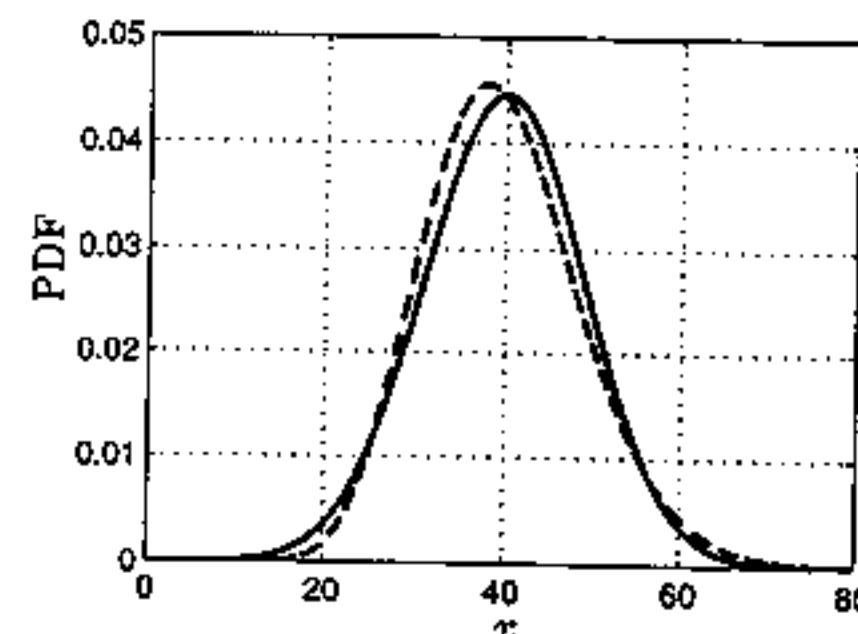
(a)  $N = 10$ (b)  $N = 40$ 

Figure 15.9:  $\chi_N^2$  PDF (dashed curve) and Gaussian PDF approximation of  $N(N, 2N)$  (solid curve).

"PROOF" OF CLT : LET  $Z_N = \frac{S_N - N E_x(x)}{\sqrt{N \text{VAR}(x)}}$

TO SHOW  $Z_N \rightarrow N(0, 1) = Z$  WE CAN  
EQUIVALENTLY SHOW THAT CHARACTERISTIC  
FUNCTION  $\phi_{Z_N}(w) \rightarrow \phi_Z(w) = e^{-\frac{1}{2}w^2}$  ← FROM  
(RECALL CHARACTERISTIC FUNCTION IS  
FOURIER TRANSFORM OF PDF)

$$\phi_{Z_N}(w) = E_{Z_N}[e^{jwZ_N}]$$

$$= E_x \left[ e^{jw \frac{\sum x_i - N E_x(x)}{\sqrt{N \text{VAR}(x)}}} \right] \quad \text{RECALL } Y = g(X) \\ E_y[y] = E_x[g(x)]$$

$$= E_x \left[ \prod_{i=1}^N e^{jw \frac{x_i - E_x(x)}{\sqrt{N \text{VAR}(x)}}} \right]$$

$$= \prod_{i=1}^N E_{x_i} \left[ e^{jw \frac{x_i - E_x(x)}{\sqrt{N \text{VAR}(x)}}} \right] \quad X, Y \text{ IND.} \Rightarrow \\ E_{xy}[g(x)h(y)] = E_x[g(x)]E_y[h(y)]$$

$$= \left[ E_x \left[ e^{jw \frac{x - E_x(x)}{\sqrt{\text{VAR}(x)}}} \right] \right]^N \quad x_i's \text{ SAME PDF} \\ \Rightarrow \text{SAME } E_x[g(x)]$$

NOW  $e^z = \sum_{k=0}^{\infty} \frac{z^k}{k!}$

$$\Rightarrow E_x \left[ e^{jw \frac{x - E_x(x)}{\sqrt{\text{VAR}(x)}}} \right] = E_x \left[ \sum_{k=0}^{\infty} \frac{(jw)^k}{k!} \left( \frac{x - E_x(x)}{\sqrt{\text{VAR}(x)}} \right)^k \right]$$

$$= \sum_{k=0}^{\infty} \frac{(jw)^k}{k!} E_x \left[ \left( \frac{x - E_x(x)}{\sqrt{\text{VAR}(x)}} \right)^k \right]$$

$$= 1 + jw E_x \left[ \frac{x - E_x(x)}{\sqrt{\text{VAR}(x)}} \right] + \frac{1}{2} (jw)^2 E_x \left[ \left( \frac{x - E_x(x)}{\sqrt{\text{VAR}(x)}} \right)^2 \right]$$

+ HIGHER ORDER TERMS IN  $1/\sqrt{N}$

$$\text{BUT } E_x \left[ \frac{x - E_x(x)}{\sqrt{N \text{VAR}(x)}} \right] = 0$$

$$E_x \left[ \left( \frac{x - E_x(x)}{\sqrt{N \text{VAR}(x)}} \right)^2 \right] = \frac{E_x [(x - E_x(x))^2]}{N \text{VAR}(x)}$$

$$= \frac{1}{N}$$

$$\phi_{Z_N}(\omega) = \left(1 + \frac{1}{2} (\gamma \omega)^2 / N\right)^N \quad \begin{matrix} \text{DROP HIGHER} \\ \text{ORDER TERMS} \end{matrix}$$

$$= \left(1 - \frac{1}{2} \omega^2 T_N\right)^N$$

$$\rightarrow e^{-\frac{1}{2} \omega^2} \quad \text{As } N \rightarrow \infty \quad (\text{SEE PROB. 5.15})$$

$$= \phi_Z(\omega) \quad Z \sim N(0, 1)$$


---

## CHAPTER 16 - BASIC RANDOM PROCESSES

STUDIED RANDOM VARIABLE  $X$

RANDOM VECTOR  $(X_1, X_2, \dots, X_N)$

NOW RANDOM PROCESS  $(x_1, x_2, x_3, x_4, \dots)$

### EXAMPLES :

WHAT IS OF  
INTEREST  
HERE?

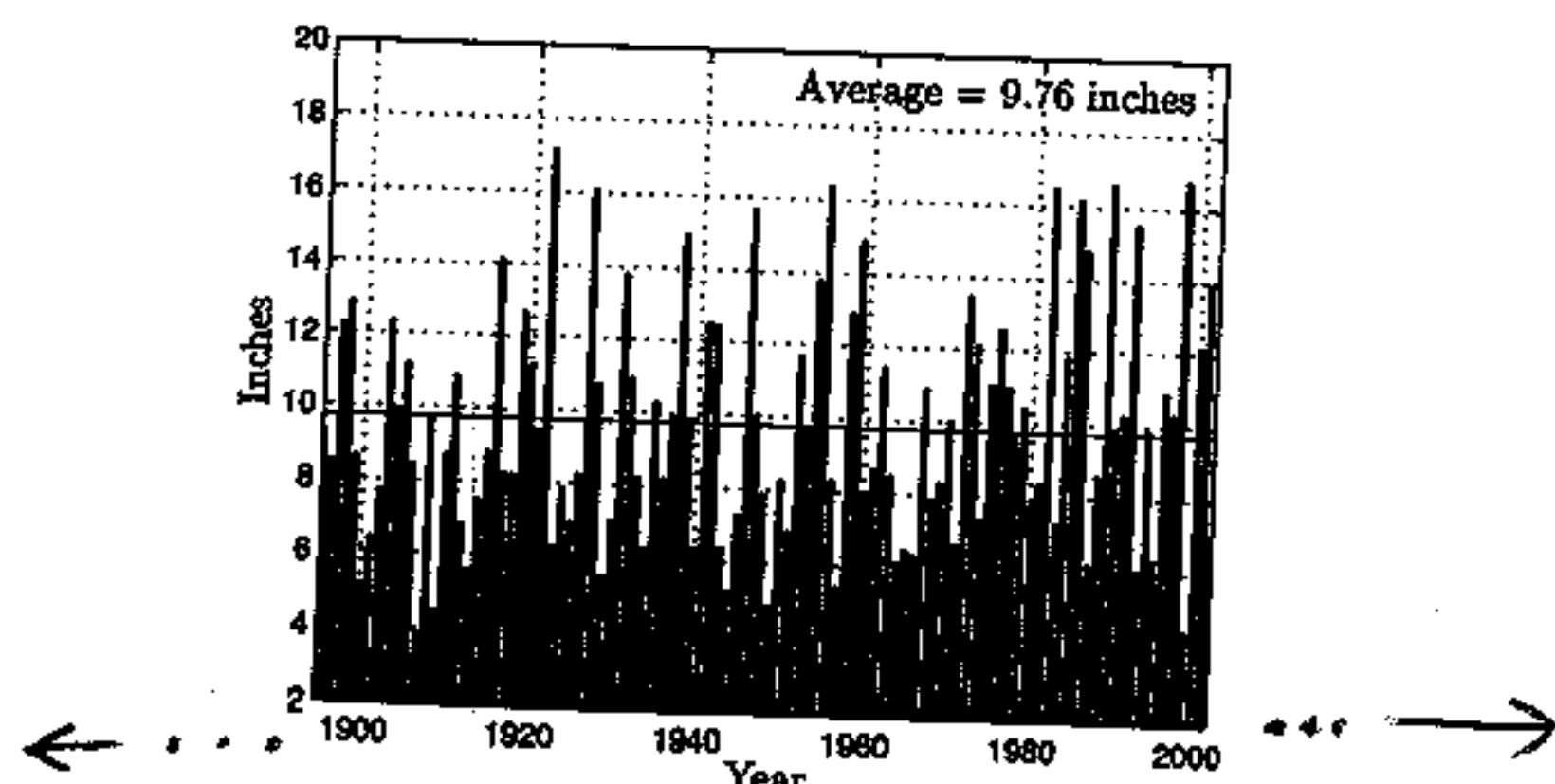
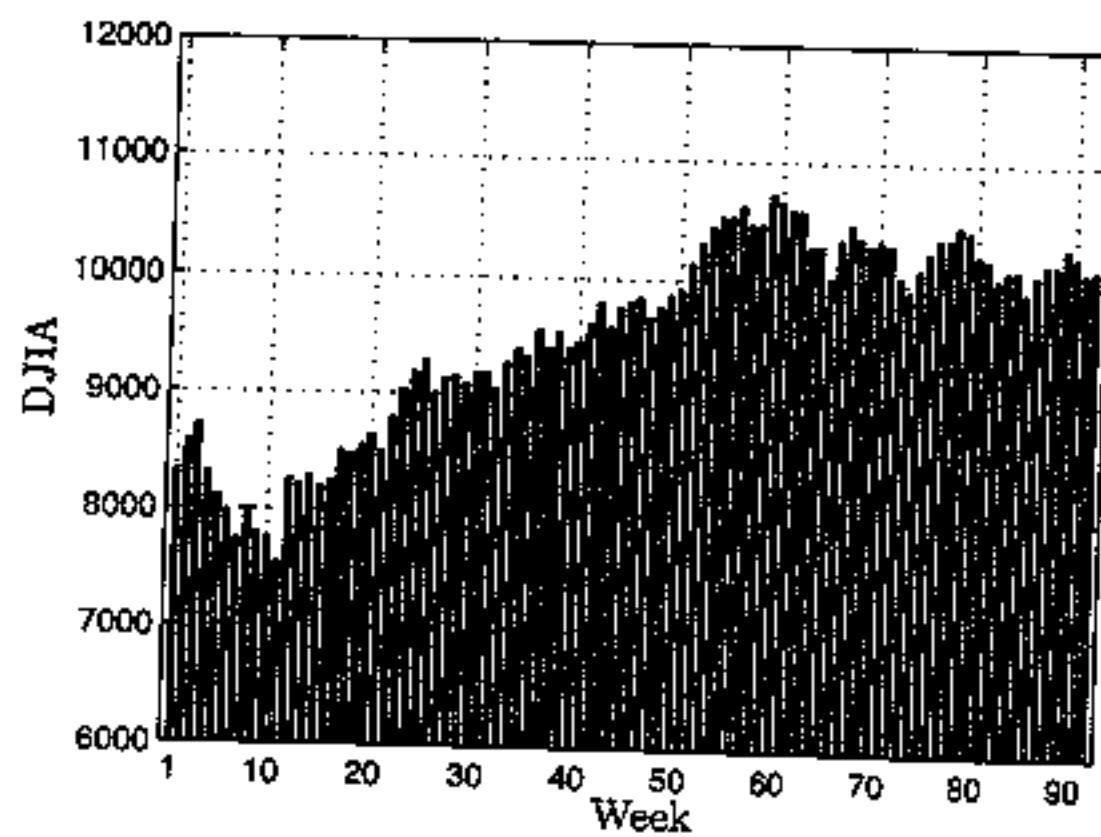


Figure 16.1: Annual summer rainfall in Rhode Island from 1895 to 2002.



WHAT IS OF  
INTEREST HERE?

Figure 16.2: Dow-Jones industrial average at the end of each week from January 8, 2003 to September 29, 2004 [DowJones.com 2004].

WHAT IS A RANDOM PROCESS (RP)?

EXAMPLE: START TOSSED COIN AT  
SOME TIME  $n=0$  AND CONTINUE  
INDEFINITELY ( $n=0, 1, 2, \dots$ )

$\Rightarrow$  INFINITE SEQUENCE OF COIN TOSSES

OUTCOMES ARE

$$S = \{ (H, H, T, \dots), (H, T, H, \dots), (T, T, H, \dots), \dots \}$$

IF WE DEFINE A R.V. AS

$$\begin{aligned} X = 0 & \text{ IF TAIL } \\ 1 & \text{ IF HEAD } \end{aligned} \quad \left. \begin{array}{l} \} \text{BERNOULLI} \\ \} RV \end{array} \right.$$

THEN WE CALL THIS A BERNOULLI RP.

THE OUTCOMES OF THE RANDOM PROCESS  
ARE

$$\mathcal{S}_x = \{(1, 1, 0, \dots), (1, 0, 1, \dots), (0, 0, 1, \dots), \dots\}$$

NOW DENOTE THE RANDOM VARIABLES  
AS  $X[0], X[1], \dots$  AND THEIR OUTCOMES  
AS  $x[0], x[1], \dots$  OR IN GENERAL  $X(n), x[n]$

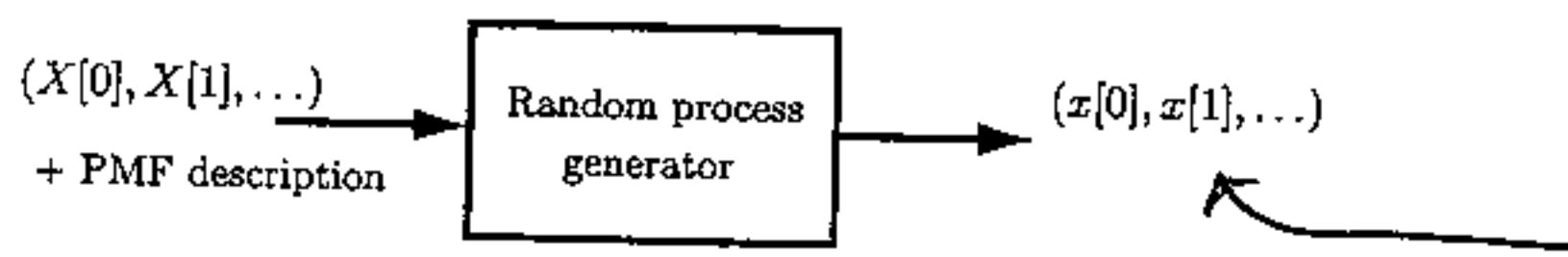


Figure 16.3: A conceptual random process generator. The input is an infinite sequence of random variables with their probabilistic description and the output is an infinite sequence of numbers.

CALLED AN  
OUTCOME OR  
SAMPLE SEQUENCE

OR REALIZATION

NOTE: EACH REALIZATION  
IS AN INFINITE SEQUENCE  
OF NUMBERS

↑ OUR CHOICE

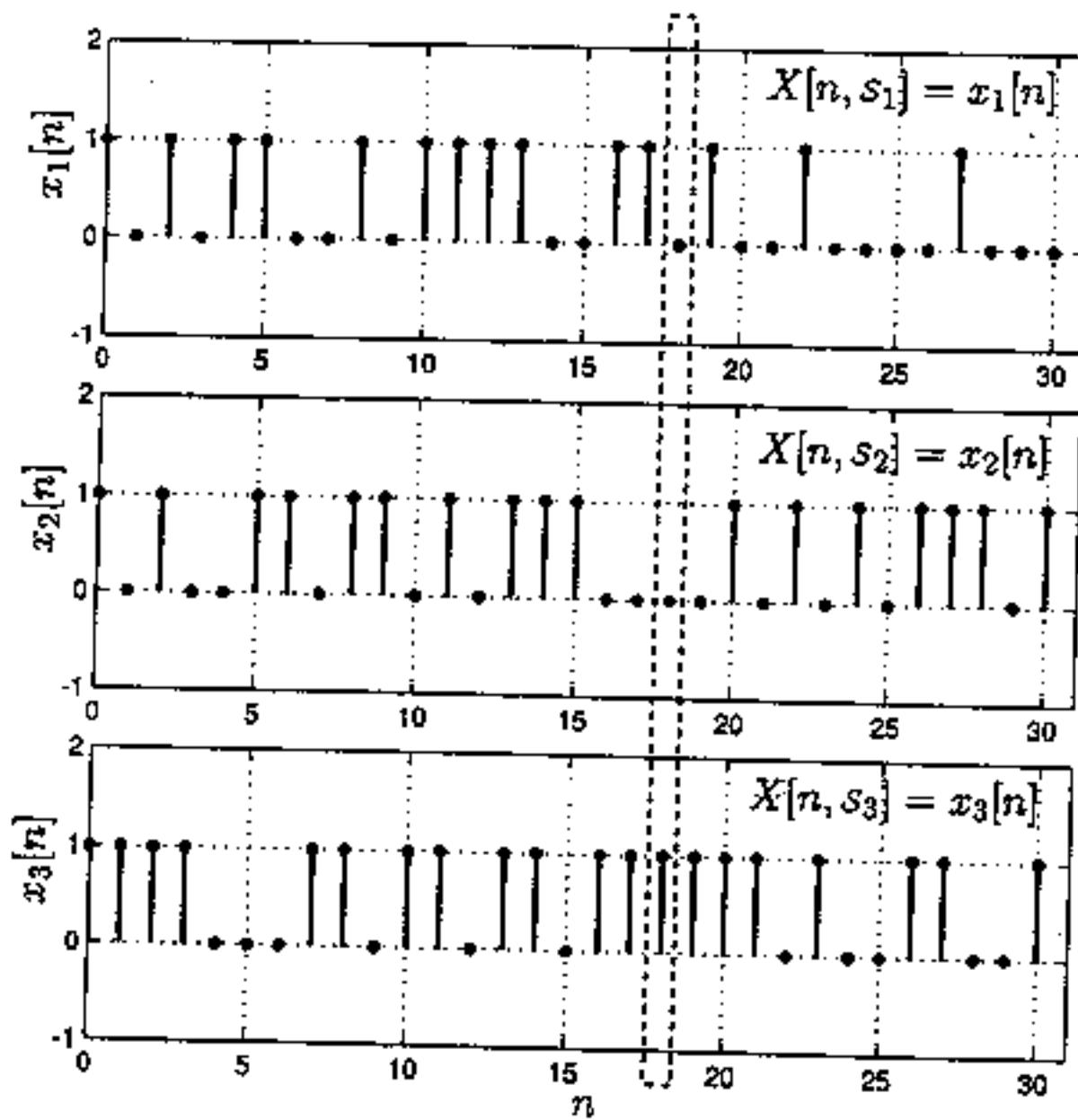
RECALL FOR A SINGLE R.V., A MAPPING  
FROM  $\mathcal{S}$  TO  $\mathcal{S}_x$ , WE DENOTE IT MORE  
EXPLICITLY AS THE SET FUNCTION  $X(S)$ .

NOW  $\mathcal{S}$  = SET OF INFINITE EXPERIMENTAL  
OUTCOMES (COIN TOSSES)

$\mathcal{S}_x$  = SET OF INFINITE SEQUENCES OF  
1'S AND 0'S (REALIZATIONS)

SET OF ALL REALIZATION CALLED  
THE ENSEMBLE OF REALIZATIONS.

NOW INSTEAD OF  $X(s)$ , USE  $X(n, s) =$   
MAPPING FROM  $s$  TO  $s_x$ .  $\forall 0 \leq n < \infty$



← FIRST REALIZATION

← SECOND REALIZATION

NOTE THAT  $X(18, s)$   
IS JUST A R.V.  $\Rightarrow$   
HAS A PDF, MEAN,  
VARIANCE, ETC.

WILL DENOTE THE R.P. BY  $X(n)$  (DROP  
THE  $s$ )

↑  
BRACKET  $\Rightarrow$   
DISCRETE-TIME OR  
FOR  $n = 0, 1, \dots$  AS  
OPPOSED TO  $X(t)$   
 $t \geq 0$

ALSO,  $X(n)$  WILL DENOTE  
THE ENTIRE R.P.

$\{X(0), X(1), \dots\}$

SOMETIMES AUTHORS USE  $\{X(n)\}_{n=0,1,\dots}$   
AND  $X(n_0)$  WILL DENOTE R.P. AT  
FIXED TIME  $n = n_0$

EXAMPLE: BERNoulli R.P. (IID TOSSES)  
 WHAT IS PROB. OF FIRST 5 TOSSES  
 COMING UP HEADS?

$$P\{x_{(0)}=1, x_{(1)}=1, x_{(2)}=1, x_{(3)}=1, x_{(4)}=1, \\ x_{(5)}=0 \text{ OR } 1, x_{(6)}=0 \text{ OR } 1, \dots\}$$

SINCE WE DON'T CARE WHAT  $x_{(n)}$  FOR  $n \geq 5$  IS,  
 WE CAN RESTRICT ATTENTION TO

$$P\{x_{(0)}=1, x_{(1)}=1, x_{(2)}=1, x_{(3)}=1, x_{(4)}=1\} \\ = \prod_{n=0}^4 P\{x_{(n)}=1\} = p^5$$

IN ESSENCE WE REPLACED R.P. BY RANDOM VECTOR  
 $\Rightarrow$  EASY PROB. COMPUTATION

WHAT IS PROB. OF EVER OBSERVING 5  
 CONSECUTIVE HEADS = 1? HOW TO FIND THIS?

### TYPES OF RANDOM PROCESSES

$x[n]$   $n = 0, 1, \dots$  SEMI-INFINITE

$x[n]$   $n = \dots, -1, 0, 1, \dots$  INFINITE

$x[n]$  DISCRETE-TIME

$x(t)$  CONTINUOUS-TIME  $-\infty < t < \infty$

CAN ALSO CATEGORIZE ACCORDING TO  
DISCRETE OR CONT. OUTCOMES ( SAME AS  
DISCRETE OR CONT. RV'S )

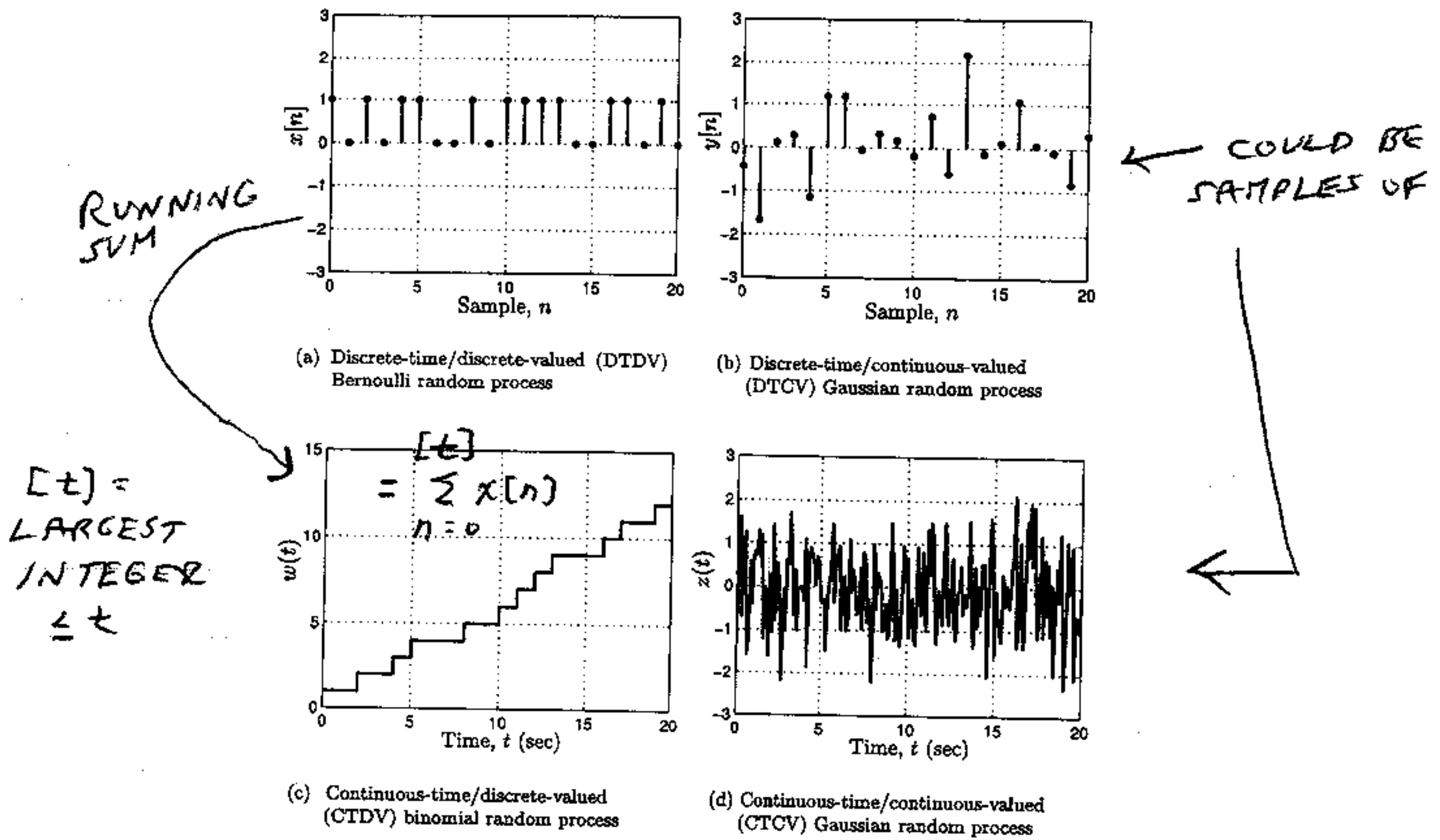


Figure 16.5: Typical realizations of different types of random processes.

WILL GENERALLY FOCUS ON (b) SINCE  
DISCRETE-TIME USED EXTENSIVELY  
IN PRACTICE AND CONT.-VALUED  
OUTCOMES CORRESPOND TO CONT. RV'S  
WHICH WE HAVE ALREADY STUDIED

EXAMPLE : RANDOM WALK ( USED AS  
MODEL FOR MANY PHYSICAL PROCESSES -  
"A RANDOM WALK DOWN WALL STREET" )

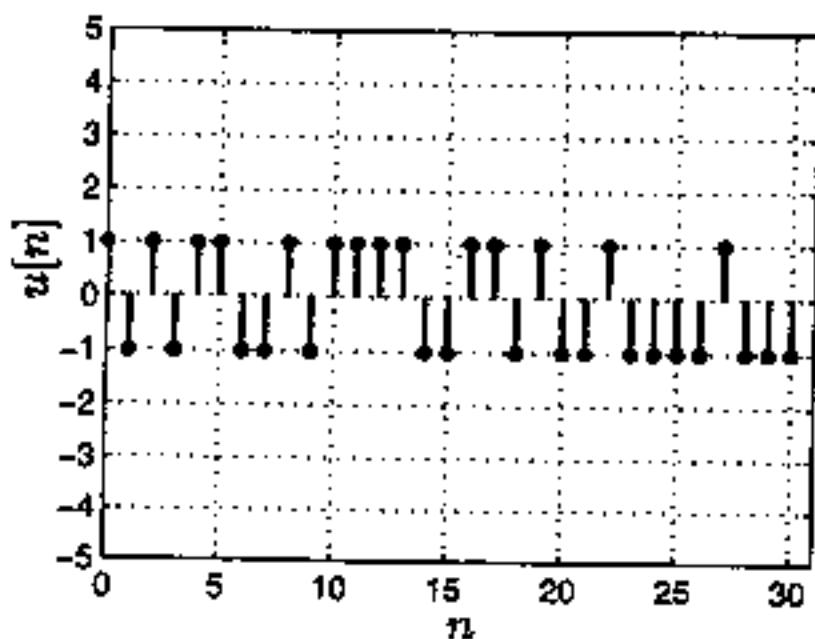
DEFINED AS  $X[n] = \sum_{i=0}^n U[i]$   $n = 0, 1, \dots$

$U[n]$  IS BERNoulli WITH OUTCOMES  $\pm 1$

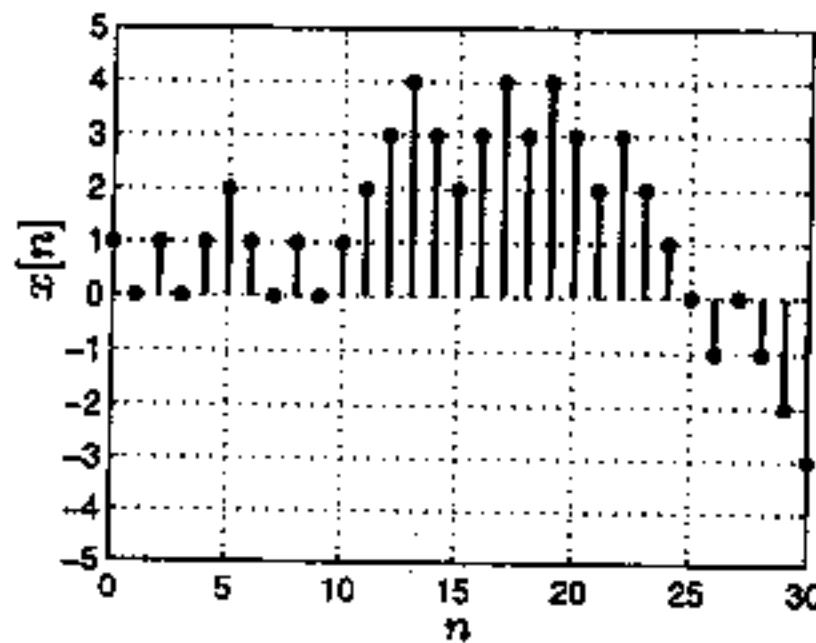
$$\text{AND } p_U[k] = \begin{cases} \frac{1}{2} & k = -1 \\ \frac{1}{2} & k = 1 \end{cases}$$

AND  $U[n]$ 'S ARE IID (BERNOULLI RP)

$\pm 1$  OUTCOMES  
INSTEAD OF  $0, 1$ )



(a) Realization of Bernoulli random process  $U[n]$



(b) Realization of random walk  $X[n]$

POSITION OF DRUNK AFTER  $n$  STEPS, PRICE OF STOCK THAT MOVES UP OR DOWN BY \$1.  
(PRICE CHANGES UNPREDICTABLE?)

AN IMPORTANT QUESTION  
IS BEHAVIOR FOR LARGE  $n$ .

BY CLT (WHY?)  $X[n] \sim \text{GAUSSIAN}$

$$E[X[n]] = E\left[\sum_{i=0}^n U[i]\right] = (n+1)E[U[0]] = 0$$

$$\text{VAR}(X[n]) = \text{VAR}\left(\sum_{i=0}^n U[i]\right) = (n+1)\underbrace{\text{VAR}(U[0])}_{=1}$$

$$\text{VAR}(U[0]) = \underbrace{E[U^2[0]]}_{=1} - \underbrace{E^2[U[0]]}_{=0} = 1$$

$\Rightarrow X[n] \sim N(0, n+1)$  MAKE SENSE?

## STATIONARITY

DO CHARACTERISTICS OF RP CHANGE WITH TIME?  
 BERNoulli RP - NO  
 RANDOM WALK - YES

TO QUANTIFY THIS NEED TO DESCRIBE PROBABILITIES OF RP. AND EXAMINE THEM OVER TIME.

### EXAMPLE : BERNoulli RP

THIS IS EXAMPLE OF IID RP.

TO COMPUTE PROBS. MUST CONSTRAIN OURSELVES TO A FINITE SET OF TIMES.

$$P_{X[n_1], X[n_2], \dots, X[n_N]} [x_1, x_2, \dots, x_N] = \prod_{i=1}^N P_{X[n_i]} [x_i]$$

JOINT PMF

CALLED A FINITE DIMENSIONAL DISTRIBUTION.

NOTE HERE THAT PROB OF FIRST 5 SAMPLES  $n_1 = 0, n_2 = 1, \dots, n_5 = 4$  BEING ALL 1's IS  $p^5$  AND PROB. OF SECOND 5 SAMPLES  $n_6 = 5, \dots, n_{10} = 9$  BEING ALL 1's IS ALSO  $p^5$ , ETC.

THIS R.P. IS STATIONARY. NOTE THAT

$$P_{X(0), \dots, X(4)} = P_{X(5), \dots, X(9)}$$

OR  $P_{X(n), \dots, X(n+4)} = P_{X(n+n_0), \dots, X(n+4+n_0)}$

$n=0$   
 $n_0=5$

IN GENERAL, A R.P. IS DEFINED TO BE STATIONARY IF

$$P_{X(n_1+n_0), X(n_2+n_0), \dots, X(n_N+n_0)} = P_{X(n_1), X(n_2), \dots, X(n_N)}$$

FOR ALL  $n_1, n_2, \dots, n_N$  (ALL  $n$ ) AND ALL  $n_0$

EVERY FINITE DIMENSIONAL DISTRIBUTION (GIVEN  $n_1, n_2, \dots, n_N$ ) DOES NOT CHANGE IF SAMPLE TIMES ARE ALL SHIFTED BY  $n_0$ .

EXAMPLE : IID R.P. IS STATIONARY

$$P_{X(n_1+n_0), \dots, X(n_N+n_0)} = \prod_{i=1}^N P_{X(n_i+n_0)} \quad \text{IND.}$$

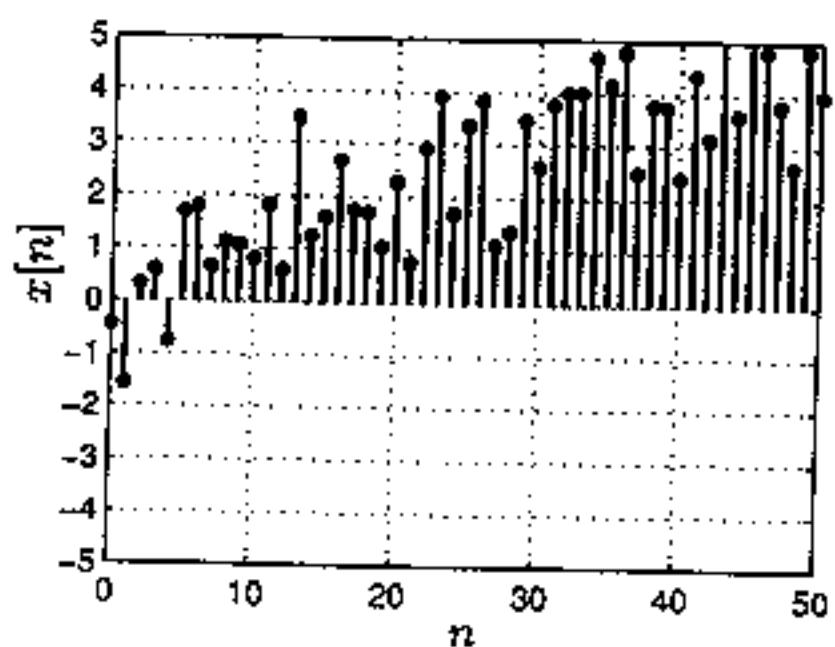
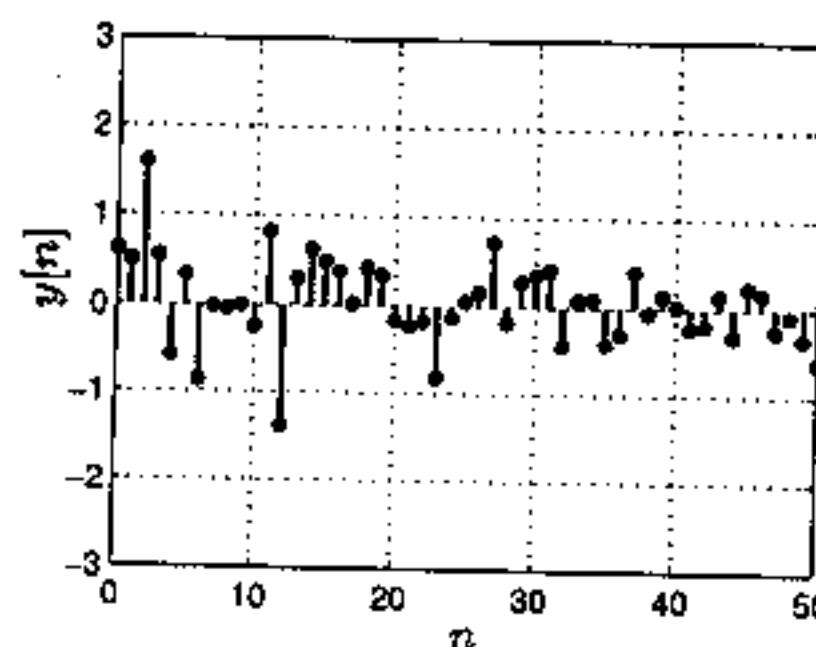
$$= \prod_{i=1}^N P_{X(n_i)} \quad \text{IDENTICALLY DIST.}$$

$$= P_{X(n_1), \dots, X(n_N)} \quad \text{IND.}$$

NOTE THAT IF R.P. IS STATIONARY,  
SO ARE ALL JOINT MOMENTS SINCE

$$E_{x(n), x(n+1), \dots, x(n+n_0)} [\cdot] = E_{x(n), \dots, x(n+n_0)} [\cdot]$$

$\Rightarrow$  IF MOMENTS ARE NOT STATIONARY,  
THEN R.P. CANNOT BE STATIONARY.

(a) Mean increasing with  $n$ (b) Variance decreasing with  $n$ 

IF YOU JUST  
LOOK AT THESE  
REALIZATIONS, CAN  
YOU TELL IF  
R.P. IS STATIONARY?

Figure 16.7: Random processes that are not stationary.

EXAMPLE : SUM R.P.

$$x(n) = \sum_{i=0}^n v(i)$$

$v(i)$ 's IID  
ARBITRARY PMF  
OR PDF

STATIONARY?

$$E(x(n)) = (n+1)E_v[v(0)]$$

$$\text{VAR}(x(n)) = (n+1)\text{VAR}(v(0))$$

---

SOMETIMES CAN CONVERT A NONSTATIONARY  
R.P. TO STATIONARY ONE (BY PROCESSING  
IT)

PREVIOUS EXAMPLE LET  $y(n) = x(n) - x(n-1)$   
WHERE  $x(-1) = 0$ . THEN,

$$y(n) = \sum_{i=0}^n v(i) - \sum_{i=0}^{n-1} v(i) = v(n) \text{ IID} \Rightarrow \text{STATIONARY}$$

NOTE MORE GENERALLY THAT FOR

$$n_4 > n_3 \geq n_2 > n_1$$

$$x(n_2) - x(n_1) = \sum_{i=n_1+1}^{n_2} v(i) \quad \begin{array}{l} \text{CALLED} \\ \text{INCREMENT} \end{array}$$

$$x(n_4) - x(n_3) = \sum_{i=n_2+1}^{n_4} v(i) \quad \text{OF R.P.}$$

ARE IND. OF EACH OTHER AND IF

$n_4 - n_3 = n_2 - n_1$  (SAME NUMBER OF  $v(i)$  TERMS),  
THEY HAVE SAME PMF/PPF.

$x(n_2) - x(n_1)$ ,  $x(n_4) - x(n_3)$  ARE CALLED  
STATIONARY INDEPENDENT INCREMENTS.

$$\uparrow \quad x(4) - x[3] = x[2+2] - x[1+2]$$

SHIFT BY 2

ALLOWS EASIER CALCULATION OF  
PROBS - SEE EX 16.5

### MORE EXAMPLES

- 1) WHITE GAUSSIAN NOISE (WGN) - USED  
EXTENSIVELY IN RADAR/SONAR/COMMUNICATIONS

DTCV R.P.,  $X(n)$  IS IID RP.

WITH  $X(n) \sim N(0, \sigma^2)$   $-\infty < n < \infty$

SEE FIG 16.5b FOR REALIZATION.

NOTE:  $E[\alpha(n_0)] = 0$  "NOISE"

AVERAGE POWER =  $E[X^2(n_0)] = \text{VAR}(X(n_0)) = \sigma^2$   
PDF IS

$$\begin{aligned} P_{X(n_1), \dots, X(n_N)}(x_1, \dots, x_N) &= \prod_{i=1}^N P_{X(n_i)}(x_i) \\ &= \prod_{i=1}^N \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}x_i^2} \\ &= \frac{1}{(2\pi\sigma^2)^{N/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^N x_i^2} \end{aligned}$$

ALSO  $= \frac{1}{(2\pi)^{N/2} \det \Sigma^{1/2}(\Sigma)} e^{-\frac{1}{2} \underline{x}^T \Sigma^{-1} \underline{x}}$

FOR  $\Sigma = \sigma^2 I$  OR  $N(0, \sigma^2 I)$

CALLED WHITE GAUSSIAN NOISE SINCE  
ITS POWER IS EQUALLY DISTRIBUTED  
IN FREQUENCY (~ WHITE LIGHT) -  
CHAPTER 17, EX. 17.9

(MA)

2) MOVING AVERAGE R.P.

$$X(n) = \frac{1}{2} (v(n) + v(n-1)) \quad -\infty < n < \infty$$

$$X(0) = \frac{1}{2} (v(0) + v(-1))$$

$$X(1) = \frac{1}{2} (v(1) + v(0))$$

$$x(2) = \frac{1}{2}(v(2) + v(1))$$

!

AVERAGING "MOVES" IN TIME.  $v(n)$  IS WGN WITH VARIANCE  $\sigma_v^2$ .

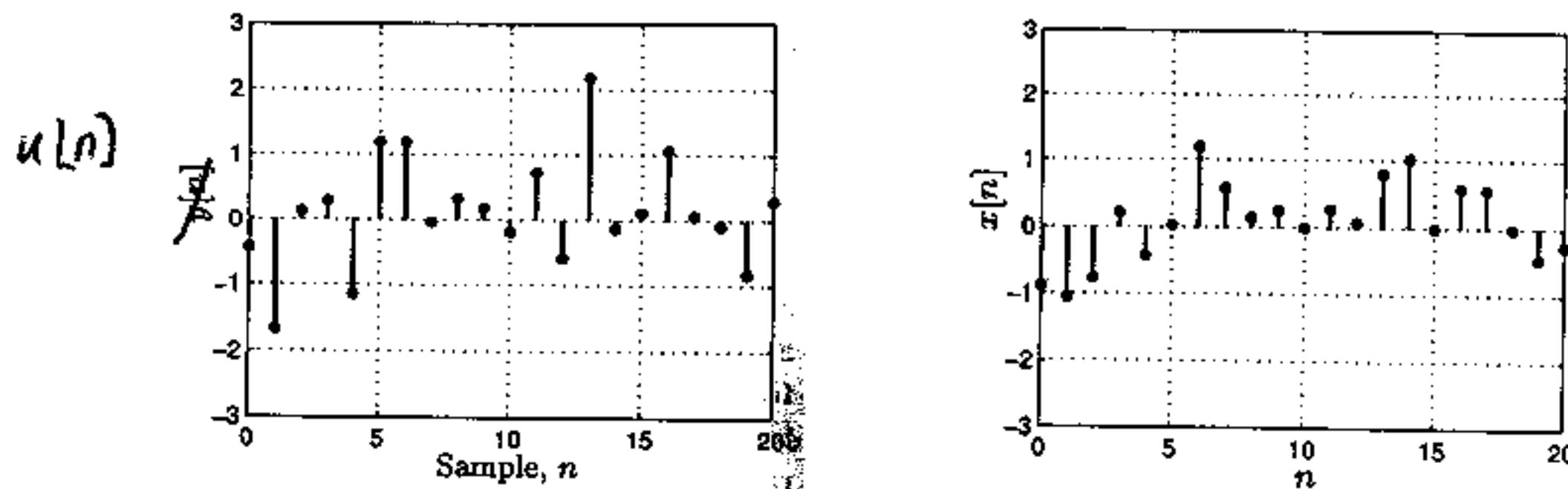


Figure 16.9: Typical realization of moving average random process. The realization of the  $U[n]$  random process is shown in Figure 16.5b.

NOTE THAT  $x[n]$  IS "SMOOTHER" (AVERAGER ACTS AS A LINEAR FILTER)

TO FIND JOINT PDF OF  $x[n]$  NOTE THAT TRANSFORMATION FROM  $v(n)$  TO  $x[n]$  IS LINEAR. FOR EXAMPLE,

$$\begin{bmatrix} x(0) \\ x(1) \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} v(-1) \\ v(0) \\ v(1) \end{bmatrix}$$

$$\underline{x} = \underline{G} \underline{v}$$

RECALL FOR WGN  $\underline{v} \sim N(\underline{0}, \sigma^2 \underline{I})$

$$\Rightarrow \underline{x} = \underline{G} \underline{v} \sim N(\underline{0}, \underline{G} \underline{C}_v \underline{G}^T)$$

$$\text{SINCE } E[\underline{x}] = E[\underline{G} \underline{v}] = \underline{G} \underbrace{E[\underline{v}]}_{\underline{0}} = \underline{0}$$

ALSO  $G \leq G^T = G \sigma^2 I \leq G^T = \sigma^2 G G^T$   
AND

$$G G^T = \begin{bmatrix} 1 & \frac{1}{4} \\ \frac{1}{4} & 1 \end{bmatrix}$$

$$\begin{pmatrix} X[0] \\ X[1] \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{bmatrix} \sigma^2/2 & \sigma^2/4 \\ \sigma^2/4 & \sigma^2/2 \end{bmatrix} \right)$$

ALSO CAN SHOW THAT THIS R.P.  
IS STATIONARY.

EXAMPLE : RANDOMLY PHASED SINUSOID

$$X[n] = \cos(2\pi(0.1)n + \Theta) \quad -\infty < n < \infty$$

WHERE  $\Theta \sim U(0, 2\pi)$

$$n = [0:31]^T$$

IN MATLAB  $x = \cos(2\pi f_0 n + 2\pi r \text{rand}(1,1))$

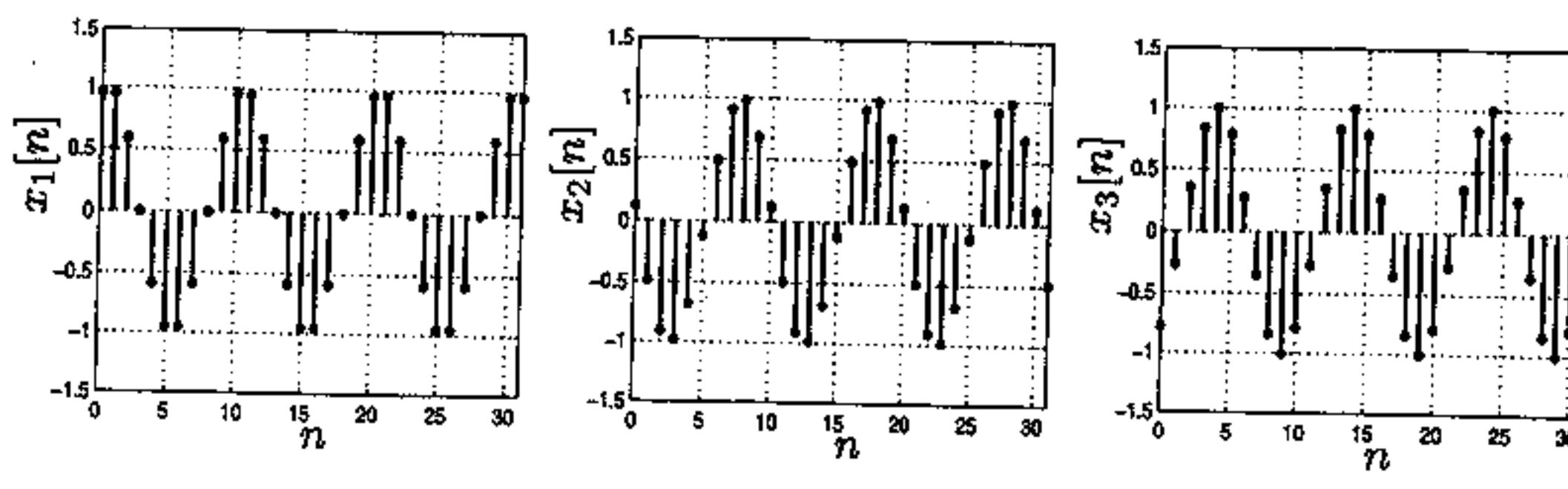


Figure 16.10: Typical realizations for randomly phased sinusoid.

NEARLY  
DETERMINISTIC -  
CAN PREDICT  
FUTURE SAMPLES  
PERFECTLY BASED  
ON PAST.