

# Rapid Estimation of the Parameters of a $K$ -Distribution

Steven Kay\*

Dept. of Electrical, Computer Engineering, and Biomedical Engineering

University of Rhode Island

Kingston, RI 02881

401-874-5804 (voice) 401-782-6422 (fax)

kay@ele.uri.edu

EDICS: 2-IDEN

April 30, 2007

## Abstract

## 1 Introduction

The  $K$ -PDF is a good model for clutter when the scatterers are not homogeneous. The random variable that describes a noise sample is given by

$$Z = \sqrt{V}U$$

where  $V$  is a Gamma distributed random variable with shape parameter  $\alpha = \nu + 1$ , and scale parameter  $\lambda = 1/2$ , and  $U$  is Gaussian with mean zero and variance  $\sigma^2$ . The random variables  $U$  and  $V$  are independent. The PDF can be shown to be

$$p_Z(z) = \frac{1}{\sqrt{\pi\sigma^2}\Gamma(\nu+1)} \left(\frac{|z|}{2\sigma}\right)^{\nu+1/2} K_{\nu+1/2}\left(\frac{|z|}{\sigma}\right) \quad -\infty < z < \infty. \quad (1)$$

In this paper we examine the use of a simple but effective estimation procedure for the parameters  $\nu$  and  $\sigma^2$ . Although the maximum likelihood estimator is the asymptotically optimal estimator, it is difficult to implement it for the  $K$ -PDF. As an alternative estimator, we use the cumulant generating function (CGF) approach as previously described in [2].

---

\*This work was supported by the Air Force Research Laboratory, Sensors Directorate, Hanscom, AFB, MA.

## 2 Estimation Method

It can easily be shown that the characteristic function for the PDF of (??) is

$$\phi_Z(\omega) = E(\exp(j\omega Z)) = \frac{1}{(1 + \omega^2 \sigma^2)^{\nu+1}} \quad (2)$$

for all  $\omega$ . As a result the CGF is

$$\begin{aligned} K_Z(\omega) &= \log[\phi_Z(\omega)] \\ &= -(\nu + 1) \log(1 + \sigma^2 \omega^2). \end{aligned} \quad (3)$$

We see that the CGF is now linear in the unknown shape parameter  $\nu$  and nonlinear in the scale parameter  $\sigma^2$ . Hence, we can estimate it by fitting the *estimated CGF* in a least squares sense. The estimated CGF is defined as

$$\hat{K}_Z(\omega) = \log\left(\frac{1}{N} \sum_{i=1}^N \cos(\omega z_i)\right) \quad (4)$$

where it is assumed that  $N$  independent and identically distributed (IID) samples of  $Z$  or  $\{z_1, z_2, \dots, z_N\}$  have been observed. Also, note that the  $K$ -PDF is an even function so that its characteristic function and hence its CGF is real. To estimate  $\nu$  we minimize the least squares error

$$J(\nu, \sigma^2) = \sum_{k=0}^M \left( \hat{K}_Z(\omega_k) - K_Z(\omega_k) \right)^2 \quad (5)$$

over a suitable range of  $\omega$ 's,  $\omega_0 \leq \omega \leq \omega_M$ . To do so we first minimize with respect to the linear parameter  $\nu$  of

$$\begin{aligned} J(\theta_1, \theta_2) &= \sum_{k=0}^M \left[ \hat{K}_Z(\omega_k) - \left( \underbrace{-(\nu + 1)}_{\theta_1} \log \left( 1 + \underbrace{\sigma^2}_{\theta_2} \omega_k^2 \right) \right) \right]^2 \\ &= \sum_{k=0}^M \left( \hat{K}_Z(\omega_k) - \theta_1 \log(1 + \theta_2 \omega_k^2) \right)^2 \\ &= (\hat{\mathbf{K}} - \mathbf{H}(\theta_2) \theta_1)^T (\hat{\mathbf{K}} - \mathbf{H}(\theta_2) \theta_1) \end{aligned} \quad (6)$$

where we have let

$$\hat{\mathbf{K}} = \begin{bmatrix} \hat{K}_Z(\omega_0) \\ \hat{K}_Z(\omega_1) \\ \vdots \\ \hat{K}_Z(\omega_M) \end{bmatrix} \quad \mathbf{H}(\theta_2) = \begin{bmatrix} \ln(1 + \theta_2 \omega_0^2) \\ \ln(1 + \theta_2 \omega_1^2) \\ \vdots \\ \ln(1 + \theta_2 \omega_M^2) \end{bmatrix}.$$

The minimization of  $J(\theta_1, \theta_2)$  over  $\theta_1$  produces the result [1]

$$\hat{\theta}_1 = \left( \mathbf{H}^T(\theta_2) \mathbf{H}(\theta_2) \right)^{-1} \mathbf{H}^T(\theta_2) \hat{\mathbf{K}} \quad (7)$$

which when substituted into (??) produces

$$J(\hat{\theta}_1, \theta_2) = \hat{\mathbf{K}}^T \left( \mathbf{I} - \mathbf{H}(\theta_2) \left( \mathbf{H}^T(\theta_2) \mathbf{H}(\theta_2) \right)^{-1} \mathbf{H}^T(\theta_2) \right) \hat{\mathbf{K}}$$

so that equivalently we need to *maximize*

$$L(\theta_2) = \hat{\mathbf{K}}^T \mathbf{H}(\theta_2) \left( \mathbf{H}^T(\theta_2) \mathbf{H}(\theta_2) \right)^{-1} \mathbf{H}^T(\theta_2) \hat{\mathbf{K}}$$

over  $\theta_2$ . This can be written as

$$L(\theta_2) = \frac{\left[ \sum_{k=0}^M \hat{K}_Z(\omega_k) \ln(1 + \theta_2 \omega_k^2) \right]^2}{\sum_{k=0}^M \left[ \ln(1 + \theta_2 \omega_k^2) \right]^2} \quad (8)$$

and must be maximized over  $\theta_2 > 0$  using a grid search. Once the maximizing value of  $\theta_2 = \sigma^2$  has been found, then this value is the least squares estimate  $\hat{\theta}_2 = \hat{\sigma}^2$ . With this value, the estimate of  $\theta_1$  easily follows from (??) as

$$\hat{\theta}_1 = \frac{\sum_{k=0}^M \hat{K}_Z(\omega_k) \ln(1 + \hat{\theta}_2 \omega_k^2)}{\sum_{k=0}^M \left[ \ln(1 + \hat{\theta}_2 \omega_k^2) \right]^2} \quad (9)$$

and thus,  $\hat{\nu} = -(1 + \hat{\theta}_1)$ . The only parameter that needs to be specified is the set of  $\omega$ 's for which the error is minimized over. Typically, we choose these to be equally spaced over an interval  $[0, 0.5]$ .

### 3 Computer Simulation Results

The estimator described for  $\nu$  and  $\sigma^2$  was implemented to determine its bias and variance. As a basis for comparison we also compare the performance to that of a method of moments estimator. The latter is easy to implement but has no optimality properties [1]. It is easily shown that

$$\begin{aligned} E[Z^2] &= 2(\nu + 1)\sigma^2 \\ E[Z^4] &= 12(\nu + 1)(\nu + 2)(\sigma^2)^2 \end{aligned}$$

so that solving for the unknown parameters produces

$$\begin{aligned} \sigma^2 &= \frac{E[Z^4] - 3E^2[Z^2]}{6E[Z^2]} \\ \nu &= \frac{E[Z^2]}{2\sigma^2} - 1. \end{aligned}$$

The method of moments estimator for  $\sigma^2$  and  $\nu$  is obtained by replacing the second- and fourth-order moments by the sample moments.

For the simulation we used  $\nu = 2$ ,  $\sigma^2 = 3$ ,  $N = 1000$  data samples, and  $\omega_k = 0.01k$  for  $k = 0, 1, \dots, 500$ . We searched over  $1 \leq \sigma^2 \leq 5$  in maximizing (??). To assess the variance performance we also computed the Cramer-Rao lower bound (CRLB). From [3] it was found that for  $\nu = 2$

$$\begin{aligned} CRLB(\hat{\nu}) &= \frac{620}{N} \\ CRLB(\hat{\sigma}^2) &= \frac{80(\sigma^2)^2}{N}. \end{aligned}$$

The results are shown in Table 1. Note that the CGF estimator has less bias and variance for both

Table 1: Estimator performance for  $\nu = 2$ ,  $\sigma^2 = 3$ , and  $N = 1000$

	<u><math>\nu</math> - mean</u>	<u><math>\nu</math> - variance</u>	<u><math>\sigma^2</math> - mean</u>	<u><math>\sigma^2</math> - variance</u>
Moments estimator	2.6857	3.7867	2.9198	1.5183
CGF estimator	2.3595	1.5188	2.9974	0.9557
CRLB	— — —	0.6200	— — —	0.7200

parameters. Its variance performance versus the CRLB is an increased factor of  $1.5188/0.6200 = 2.45$  for  $\nu$  and  $0.9557/0.7200 = 1.32$  for  $\sigma^2$  while that for the method of moments estimator is substantially higher.

## References

1. Kay, S., *Fundamentals of Statistical Signal Processing: Estimation Theory*, Prentice-Hall, Upper Saddle River, NJ, 1993.
2. Kay, S., D. Middleton, “Estimation of the Parameters of the Class A Models via the Cumulant Generating Function”, CISS 2002, Princeton, NJ March 2002.
3. Kay, S., C. Xu, “Cramer-Rao Lower Bound Computation via the Characteristic Function with Application to the K-Distribution”, to be published in *IEEE Trans. on Aerospace and Electronics*.