

XC4000E Electrical Specifications

Definition of Terms

In the following tables, some specifications may be designated as Advance or Preliminary. These terms are defined as follows:

Advance: Initial estimates based on simulation and/or extrapolation from other speed grades, devices, or device

families. Values are subject to change. Use as estimates, not for production.

Preliminary: Based on preliminary characterization. Further changes are not expected.

Unmarked: Specifications not identified as either Advance or Preliminary are to be considered Final.

Except for pin-to-pin input and output parameters, the a.c. parameter delay specifications included in this document are derived from measuring internal test patterns. All specifications are representative of worst-case supply voltage and junction temperature conditions.

All specifications subject to change without notice.

XC4000E DC Characteristics

Absolute Maximum Ratings

Symbol	Description		Value	Units		
V _{CC}	Supply voltage relative to GND		-0.5 to +7.0	V		
V _{IN}	Input voltage relative to GND (Note 1)	put voltage relative to GND (Note 1)				
V _{TS}	Voltage applied to 3-state output (Note 1)	-0.5 to V _{CC} +0.5	V			
T _{STG}	Storage temperature (ambient)		-65 to +150	°C		
T _{SOL}	Maximum soldering temperature (10 s @ 1/16 in. =	1.5 mm)	+260	°C		
т	Junction Temperature	Ceramic packages	+150	°C		
T_{J} J	Junction remperature	Plastic packages	+125	°C		

Note 1: Maximum DC excursion above V_{CC} or below Ground must be limited to either 0.5 V or 10 mA, whichever is easier to achieve. During transitions, the device pins may undershoot to -2.0 V or overshoot to V_{CC} + 2.0 V, provided this over or undershoot lasts less than 10 ns and with the forcing current being limited to 200 mA.

Note: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions is not implied. Exposure to Absolute Maximum Ratings conditions for extended periods of time may affect device reliability.

Recommended Operating Conditions

Symbol	Description		Min	Max	Units
V _{CC}	Supply voltage relative to GND, T _J = -0 °C to +85°C	Commercial	4.75	5.25	V
	Supply voltage relative to GND, T _J = -40°C to +100°C	Industrial	4.5	5.5	V
	Supply voltage relative to GND, T _C = -55°C to +125°C	Military	4.5	5.5	V
V	High-Level Input Voltage	TTL inputs	2.0	V _{CC}	V
V_{IH}	High-Level input voltage	CMOS inputs	70%	100%	V _{CC}
V	Low-Level Input Voltage	TTL inputs	0	0.8	V
V_{IL}	Low-Level Input Voltage	CMOS inputs	0	20%	V _{CC}
T _{IN}	Input signal transition time		250	ns	

Notes: At junction temperatures above those listed above, all delay parameters increase by 0.35% per °C. Input and output measurement thresholds for TTL are 1.5 V and for CMOS are 2.5 V.



DC Characteristics Over Operating Conditions

Symbol	Description		Min	Max	Units
V _{OH}	High-level output voltage @ I _{OH} = -4.0mA, V _{CC} min	TTL outputs	2.4		V
	High-level output voltage @ I _{OH} = -1.0mA, V _{CC} min	CMOS outputs	V _{CC} -0.5		V
V _{OL}	Low-level output voltage @ I _{OL} = 12.0mA, V _{CC} min	TTL outputs		0.4	V
	(Note 1)	CMOS outputs		0.4	V
I _{cco}	Quiescent FPGA supply current (Note 2)	Commercial		3.0	mA
		Industrial		6.0	mA
		Military		6.0	mA
ΙL	Input or output leakage current	•	-10	+10	μΑ
C _{IN}	Input capacitance (sample tested)	PQFP and MQFP		10	pF
		packages			
		Other packages		16	pF
I _{RIN*}	Pad pull-up (when selected) @ V _{IN} = 0V (sample teste	-0.02	-0.25	mA	
I _{RLL*}	Horizontal Longline pull-up (when selected) @ logic Low			2.5	mA

Notes: With 50% of the outputs simultaneously sinking 12mA, up to a maximum of 64 pins.

With no output current loads, no active input or Longline pull-up resistors, all package pins at Vcc or GND, and the FPGA configured with a Development system Tie option.

^{*}Characterized Only.



XC4000E Switching Characteristics

Testing of the switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values where one global clock input drives one vertical clock line in each accessible column, and where all accessible IOB and CLB flip-flops are clocked by the global clock net.

When fewer vertical clock lines are connected, the clock distribution is faster; when multiple clock lines per column are driven from the same global clock, the delay is longer. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature).

Global Buffer Switching Characteristic Guidelines

	S	Speed Grade	-4	-3	-2	-1	
Description	Symbol	Device	Max	Max	Max	Max	Units
From pad through	T _{PG}	XC4003E	7.0	4.7	4.0	3.5	ns
Primary buffer,		XC4005E	7.0	4.7	4.3	3.8	ns
to any clock K		XC4006E	7.5	5.3	5.2	4.6	ns
		XC4008E	8.0	6.1	5.2	4.6	ns
		XC4010E	11.0	6.3	5.4	4.8	ns
		XC4013E	11.5	6.8	5.8	5.2	ns
		XC4020E	12.0	7.0	6.4	6.0	ns
		XC4025E	12.5	7.2	6.9	_	ns
From pad through	T _{SG}	XC4003E	7.5	5.2	4.4	4.0	ns
Secondary buffer,		XC4005E	7.5	5.2	4.7	4.3	ns
to any clock K		XC4006E	8.0	5.8	5.6	5.1	ns
		XC4008E	8.5	6.6	5.6	5.1	ns
		XC4010E	11.5	6.8	5.8	5.3	ns
		XC4013E	12.0	7.3	6.2	5.7	ns
		XC4020E	12.5	7.5	6.7	6.5	ns
		XC4025E	13.0	7.7	7.2	_	ns



Horizontal Longline Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted. The following guidelines reflect worst-case values over the recommended operating conditions.

	Sp	eed Grade	-4	-3	-2	-1	
Description	Symbol	Device	Max	Max	Max	Max	Units
TBUF driving a Horizontal Longline (LL):				-			
I going High or Low to LL going High or Low, while T is Low.	T _{IO1}	XC4003E XC4005E XC4006E	5.0 5.0 6.0	4.2 5.0 5.9	3.4 4.0 4.7	2.9 3.4 4.0	ns ns ns
Buffer is constantly active. (Note1)		XC4008E XC4010E XC4013E XC4020E	7.0 8.0 9.0 10.0	6.3 6.4 7.2 8.2	5.0 5.1 5.7 7.3	4.3 4.4 4.9 5.6	ns ns ns
I going Low to LL going from resistive pull-up High to active Low. TBUF configured as open-drain. (Note1)	T _{IO2}	XC4025E XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	11.0 5.0 6.0 7.8 8.1 10.5 11.0 12.0 12.0	9.1 4.2 5.3 6.4 6.8 6.9 7.7 8.7 9.6	7.3 3.6 4.5 5.4 5.8 5.9 6.5 8.7 9.6	3.1 3.8 4.6 4.9 5.0 5.5 7.4	ns
T going Low to LL going from resistive pull-up or floating High to active Low. TBUF configured as open-drain or active buffer with I = Low. (Note1)	T _{ON}	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	5.5 7.0 7.5 8.0 8.5 8.7 11.0	4.6 6.0 6.7 7.1 7.3 7.5 8.4 8.4	3.9 5.7 5.7 6.0 6.2 7.0 7.1 7.1	3.5 4.7 4.9 5.2 5.4 6.2 6.3	ns ns ns ns ns ns ns
T going High to TBUF going inactive, not driving LL	T _{OFF}	All devices	1.8	1.5	1.3	1.1	ns
T going High to LL going from Low to High, pulled up by a single resistor. (Note 1)	T _{PUS}	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	20.0 23.0 25.0 27.0 29.0 32.0 35.0 42.0	14.0 16.0 18.0 20.0 22.0 26.0 32.5 39.1	14.0 16.0 18.0 20.0 22.0 26.0 32.5 39.1	12.0 14.0 16.0 16.0 18.0 21.0 26.0	ns ns ns ns ns ns ns
T going High to LL going from Low to High, pulled up by two resistors. (Note1)	T _{PUF}	XC4003E XC4005E XC4006E XC4008E XC4010E XC4013E XC4020E XC4025E	9.0 10.0 11.5 12.5 13.5 15.0 16.0 18.0	7.0 8.0 9.0 10.0 11.0 13.0 14.8 16.5	6.0 6.8 7.7 8.5 9.4 11.7 14.8 16.5	5.4 5.8 6.5 7.5 8.0 9.4 10.5	ns ns ns ns ns ns

Note 1: These values include a minimum load. Use the static timing analyzer to determine the delay for each destination.



Wide Decoder Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted. The following guidelines reflect worst-case values over the recommended operating conditions.

	S	Speed Grade	-4	-3	-2	-1	
Description	Symbol	Device	Max	Max	Max	Max	Units
Full length, both pull-ups,	T _{WAF}	XC4003E	9.2	5.0	5.0	4.3	ns
inputs from IOB I-pins		XC4005E	9.5	6.0	6.0	5.1	ns
		XC4006E	12.0	7.0	7.0	6.0	ns
		XC4008E	12.5	8.0	8.0	6.5	ns
		XC4010E	15.0	9.0	9.0	7.5	ns
		XC4013E	16.0	11.0	11.0	8.6	ns
		XC4020E	17.0	13.9	13.9	10.1	ns
		XC4025E	18.0	16.9	16.9	_	ns
Full length, both pull-ups,	T _{WAFL}	XC4003E	12.0	7.0	7.0	5.5	ns
inputs from internal logic		XC4005E	12.5	8.0	8.0	6.4	ns
		XC4006E	14.0	9.0	9.0	7.0	ns
		XC4008E	16.0	10.0	10.0	7.5	ns
		XC4010E	18.0	11.0	11.0	8.5	ns
		XC4013E	19.0	13.0	13.0	10.0	ns
		XC4020E	20.0	15.5	15.5	11.8	ns
		XC4025E	21.0	18.9	18.9	_	ns
Half length, one pull-up,	T _{WAO}	XC4003E	10.5	6.0	6.0	5.1	ns
inputs from IOB I-pins		XC4005E	10.5	7.0	7.0	6.0	ns
		XC4006E	13.5	8.0	8.0	6.5	ns
		XC4008E	14.0	9.0	9.0	7.0	ns
		XC4010E	16.0	10.0	10.0	7.5	ns
		XC4013E	17.0	12.0	12.0	10.0	ns
		XC4020E	18.0	15.0	15.0	11.8	ns
		XC4025E	19.0	17.6	17.6	_	ns
Half length, one pull-up,	T _{WAOL}	XC4003E	12.0	8.0	8.0	6.0	ns
inputs from internal logic		XC4005E	12.5	9.0	9.0	7.0	ns
		XC4006E	14.0	10.0	10.0	7.6	ns
		XC4008E	16.0	11.0	11.0	8.4	ns
		XC4010E	18.0	12.0	12.0	9.2	ns
		XC4013E	19.0	14.0	14.0	10.8	ns
		XC4020E	20.0	16.8	16.8	12.6	ns
		XC4025E	21.0	19.6	19.6	_	ns

Note 1: These delays are specified from the decoder input to the decoder output.

Note 2: Fewer than the specified number of pullup resistors can be used, if desired. Using fewer pullups reduces power consumption but increases delays. Use the static timing analyzer to determine delays if fewer pullups are used.



XC4000E CLB Characteristics Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted

CLB Switching Characteristics Guidelines

Speed Grade)	-	4	-	3	-	2	-	1	Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Units
Combinatorial Delays										
F/G inputs to X/Y outputs	T _{ILO}		2.7		2.0		1.6		1.3	ns
F/G inputs via H to X/Y outputs	T _{IHO}		4.7		4.3		2.7		2.2	ns
C inputs via SR through H to X/Y outputs	T _{HH0O}		4.1		3.3		2.4		1.9	ns
C inputs via H to X/Y outputs	T _{HH1O}		3.7		3.6		2.2		1.6	ns
C inputs via DIN through H to X/Y outputs	T _{HH2O}		4.5		3.6		2.6		1.9	ns
CLB Fast Carry Logic										
Operand inputs (F1, F2, G1, G4) to COUT	T _{OPCY}		3.2		2.6		2.1		1.7	ns
Add/Subtract input (F3) to COUT	T _{ASCY}		5.5		4.4		3.7		2.5	ns
Initialization inputs (F1, F3) to COUT	T _{INCY}		1.7		1.7		1.4		1.2	ns
CIN through function generators to	T _{SUM}		3.8		3.3		2.6		1.8	ns
X/Y outputs										
CIN to COUT, bypass function generators	T _{BYP}		1.0		0.7		0.6		0.5	ns
Sequential Delays		'	•							
Clock K to outputs Q	T _{CKO}		3.7		2.8		2.8		1.9	ns
Setup Time before Clock K		'	•							
F/G inputs	T _{ICK}	4.0		3.0		2.4		1.8		ns
F/G inputs via H	T _{IHCK}	6.1		4.6		3.9		2.8		ns
C inputs via H0 through H	T _{HH0CK}	4.5		3.6		3.5		2.4		ns
C inputs via H1 through H	T _{HH1CK}	5.0		4.1		3.3		2.1		ns
C inputs via H2 through H	T _{HH2CK}	4.8		3.8		3.7		2.5		ns
C inputs via DIN	T _{DICK}	3.0		2.4		2.0		1.0		ns
C inputs via EC	T _{ECCK}	4.0		3.0		2.6		2.0		ns
C inputs via S/R, going Low (inactive)	T _{RCK}	4.2		4.0		4.0		1.5		ns
C _{IN} input via F/G	T _{CCK}	2.5		2.1						ns
C _{IN} input via F/G and H	T _{CHCK}	4.2		3.5						ns



XC4000E CLB Characteristics Guidelines (Continued)

Speed Grad	de	-	4	-	3	-	2	-	1	Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Units
Hold Time after Clock K				•	•					
F/G inputs	T _{CKI}	0		0		0		0		ns
F/G inputs via H	T _{CKIH}	0		0		0		0		ns
C inputs via H0 through H	T _{CKHH0}	0		0		0		0		ns
C inputs via H1 through H	T _{CKHH1}	0		0		0		0		ns
C inputs via H2 through H	T _{CKHH2}	0		0		0		0		ns
C inputs via DIN	T _{CKDI}	0		0		0		0		ns
C inputs via EC	T _{CKEC}	0		0		0		0		ns
C inputs via SR, going Low (inactive)	T _{CKR}	0		0		0		0		ns
Clock					'					
Clock High time	T _{CH}	4.5		4.0		4.0		3.0		ns
Clock Low time	T _{CL}	4.5		4.0		4.0		3.0		ns
Set/Reset Direct										
Width (High)	T _{RPW}	5.5		4.0		4.0		3.0		ns
Delay from C inputs via S/R,	T _{RIO}		6.5		4.0		4.0		3.0	ns
going High to Q										
Master Set/Reset (Note 1)										
Width (High or Low)	T _{MRW}	13.0		11.5		11.5		10.0		ns
Delay from Global Set/Reset net to Q	T _{MRQ}		23.0		18.7		17.4		15.0	ns
Global Set/Reset inactive to first	T _{MRK}									
active clock K edge										
Toggle Frequency (Note 2)	F _{TOG}		111		125		125		166	MHz

Note 1: Timing is based on the XC4005E. For other devices see the static timing analyzer.

Note 2: Export Control Max. flip-flop toggle rate.



CLB Edge-Triggered (Synchronous) RAM Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

Single Port RAM	Spee	d Grade	-	4	-	3	-	2	-1		Units
Single Fort IXAW	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Ullics
Write Operation		'	'	•	•	•					
Address write cycle time (clock K period)	16x2 32x1	T _{WCS}	15.0 15.0		14.4 14.4		11.6 11.6		8.0 8.0		ns ns
Clock K pulse width (active edge)	16x2 32x1	T _{WPS}	7.5 7.5	1 ms 1 ms	7.2 7.2	1 ms 1 ms	5.8 5.8	1 ms 1 ms	4.0 4.0		ns ns
Address setup time before clock K	16x2 32x1	T _{ASS} T _{ASTS}	2.8 2.8		2.4 2.4		2.0 2.0		1.5 1.5		ns ns
Address hold time after clock K	16x2 32x1	T _{AHS} T _{AHTS}	0 0		0 0		0 0		0 0		ns ns
DIN setup time before clock K	16x2 32x1	T _{DSS} T _{DSTS}	3.5 2.5		3.2 1.9		2.7 1.7		1.5 1.5		ns ns
DIN hold time after clock K	16x2 32x1	T _{DHS} T _{DHTS}	0 0		0 0		0 0		0 0		ns ns
WE setup time before clock K	16x2 32x1	T _{WSS} T _{WSTS}	2.2 2.2		2.0 2.0		1.6 1.6		1.5 1.5		ns ns
WE hold time after clock K	16x2 32x1	T _{WHS}	0 0		0 0		0 0		0 0		ns ns
Data valid after clock K	16x2 32x1	T _{WOS}		10.3 11.6		8.8 10.3		7.9 9.3		6.5 7.0	ns ns

Note 1: Timing for the 16x1 RAM option is identical to 16x2 RAM timing.

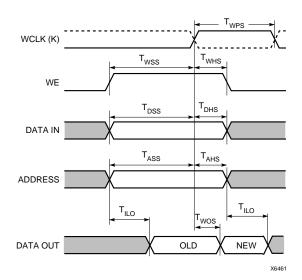
Note 2: Applicable Read timing specifications are identical to Level-Sensitive Read timing.

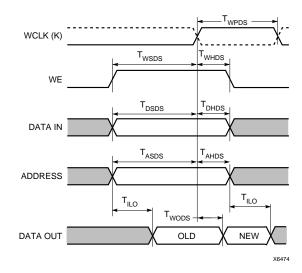
Dual-Port RAM	Spee	Speed Grade		-4		-3		2	-1		Units
Buai-i Oit IVAIVI	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Uiilla
Write Operation				•	•						
Address write cycle time (clock K period)	16x1	T _{WCDS}	15.0		14.4		11.6		8.0		ns
Clock K pulse width (active edge)	16x1	T _{WPDS}	7.5	1 ms	7.2	1 ms	5.8	1 ms	4.0		ns
Address setup time before clock K	16x1	T _{ASDS}	7.5		2.5		2.1		1.5		ns
Address hold time after clock K	16x1	T _{AHDS}	2.8		0		0		0		ns
DIN setup time before clock K	16x1	T _{DSDS}	0		2.5		1.6		1.5		ns
DIN hold time after clock K	16x1	T _{DHDS}	2.2		0		0		0		ns
WE setup time before clock K	16x1	T _{WSDS}	0		1.8		1.6		1.5		ns
WE hold time after clock K	16x1	T _{WHDS}	2.2		0		0		0		ns
Data valid after clock K	16x1	T _{WODS}	0.3	10.0		7.8		7.0		6.5	ns

Note: Applicable Read timing specifications are identical to Level-Sensitive Read timing



CLB RAM Synchronous (Edge-Triggered) Write Timing Waveforms





Single Port

Dual Port



CLB Level-Sensitive RAM Switching Characteristic Guidelines

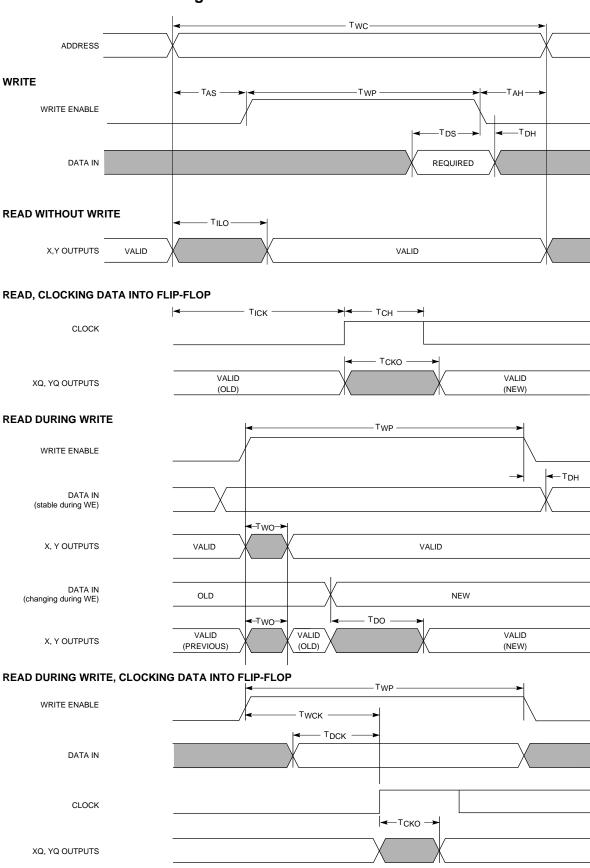
Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

	Spe	eed Grade	-	4	-	3	-:	2	-	1	Units
Description	Size	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Units
Write Operation		1									
Address write cycle time	16x2 32x1	T _{WC}	8.0 8.0		8.0 8.0		8.0 8.0		8.0 8.0		ns ns
Write Enable pulse width (High)	16x2 32x1	T _{WP} T _{WPT}	4.0 4.0		4.0 4.0		4.0 4.0		4.0 4.0		ns ns
Address setup time before WE	16x2 32x1	T _{AS} T _{AST}	2.0 2.0		2.0 2.0		2.0 2.0		2.0 2.0		ns ns
Address hold time after end of WE	16x2 32x1	T _{AH} T _{AHT}	2.5 2.0		2.0 2.0		2.0 2.0		2.0 2.0		ns ns
DIN setup time before end of WE	16x2 32x1	T _{DS} T _{DST}	4.0 5.0		2.2 2.2		0.8		0.8 0.8		ns ns
DIN hold time after end of WE	16x2 32x1	T _{DH} T _{DHT}	2.0 2.0		2.0 2.0		2.0 2.0		2.0 2.0		ns ns
Read Operation											
Address read cycle time	16x2 32x1	T _{RC} T _{RCT}	4.5 6.5		3.1 5.5		2.6 3.8		2.6 3.8		ns ns
Data valid after address change (no Write Enable)	16x2 32x1	T _{ILO} T _{IHO}		2.7 4.7		1.8 3.2		1.6 2.7		1.6 2.7	ns ns
Read Operation, Clocking Data into	Flip-Fl	ор									
Address setup time before clock K	16x2 32x1	T _{ICK} T _{IHCK}	4.0 6.1		3.0 4.6		2.4 3.9		2.4 3.9		ns ns
Read During Write		1						'			
Data valid after WE goes active (DIN stable before WE)	16x2 32x1	T _{WO}		10.0 12.0		6.0 7.3		4.9 5.6		4.9 5.6	ns ns
Data valid after DIN (DIN changes during WE)	16x2 32x1	T _{DO} T _{DOT}		9.0 11.0		6.6 7.6		5.8 6.2		5.8 6.2	ns ns
Read During Write, Clocking Data into Flip-Flop											
WE setup time before clock K	16x2 32x1	T _{WCK}	8.0 9.6		6.0 6.8		5.1 5.8		5.1 5.8		ns ns
Data setup time before clock K	16x2 32x1	T _{DCK}	7.0 8.0		5.2 6.2		4.4 5.3		4.4 5.3		ns ns

Note 1: Timing for the 16x1 RAM option is identical to 16x2 RAM timing.



CLB Level-Sensitive RAM Timing Waveforms



X2640



XC4000E Guaranteed Input and Output Parameters (Pin-to-Pin, TTL I/O)

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. Values apply to all XC4000E devices unless otherwise noted.

	Spe	ed Grade	-4	-3	-2	-1	I I in it o
Description	Symbol	Device					Units
Global Clock to Output (fast) using OFF	T _{ICKOF}	XC4003E XC4005E XC4006E	12.5 14.0 14.5	10.2 10.7 10.7	8.7 9.1 9.1	5.8 6.2 6.4	ns ns ns
Global Clock-to-Output Delay TPG OFF X3202	(Max)	XC4008E XC4010E XC4013E XC4020E XC4025E	15.0 16.0 16.5 17.0 17.0	10.8 10.9 11.0 11.0 12.6	9.2 9.3 9.4 10.2 10.8	6.6 6.8 7.2 7.4	ns ns ns ns
Global Clock to Output (slew-limited) using OFF	T _{ICKO}	XC4003E XC4005E XC4006E	16.5 18.0 18.5	14.0 14.7 14.7	11.5 12.0 12.0	7.8 8.2 8.4	ns ns ns
Global Clock-to-Output Delay Signature of the control of the cont	(Max)	XC4008E XC4010E XC4013E XC4020E XC4025E	19.0 20.0 20.5 21.0 21.0	14.8 14.9 15.0 15.1 15.3	12.1 12.2 12.8 12.8 13.0	8.6 8.8 9.2 9.4 —	ns ns ns ns
Input Setup Time, using IFF (no delay)	T _{PSUF}	XC4003E XC4005E XC4006E	2.5 2.0 1.9	2.3 1.2 1.0	2.3 1.2 1.0	1.5 0.8 0.6	ns ns ns
Set - Up & IFF & I	(Min)	XC4008E XC4010E XC4013E XC4020E XC4025E	1.4 1.0 0.5 0	0.6 0.2 0 0	0.6 0.2 0 0	0.2 0 0 0 -	ns ns ns ns ns
Input Hold Time, using IFF (no delay)	T _{PHF}	XC4003E XC4005E XC4006E	4.0 4.6 5.0	4.0 4.5 4.7	4.0 4.5 4.7	1.5 2.0 2.0	ns ns ns
Set - Ug Hold Time	(Min)	XC4008E XC4010E XC4013E XC4020E XC4025E	6.0 6.0 7.0 7.5 8.0	5.1 5.5 6.5 6.7 7.0	5.1 5.5 5.5 5.7 5.9	2.5 2.5 3.0 3.5	ns ns ns ns
Input Setup Time, using IFF (with delay)	T _{PSU}	XC4003E XC4005E XC4006E	8.5 8.5 8.5	7.0 7.0 7.0	6.0 6.0 6.0	5.0 5.0 5.0	ns ns ns
Set - Up & IFF Hold Time TPG TIME TIME TPG TIME TIME TPG TIME TIME TPG TIME TPG TIME TIME TIME TIME TIME TIME TIME TIME	(Min)	XC4008E XC4010E XC4013E XC4020E XC4025E	8.5 8.5 8.5 9.5 9.5	7.0 7.0 7.0 7.0 7.6	6.0 6.0 6.0 6.8 6.8	5.0 5.0 5.0 5.0	ns ns ns ns
Input Hold Time, using IFF (with delay)	T _{PH}	XC4003E XC4005E XC4006E	0 0 0	0 0 0	0 0 0	0 0 0	ns ns ns
Set - Up & IFF I	(Min)	XC4008E XC4010E XC4013E XC4020E XC4025E	0 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0 -	ns ns ns ns

OFF = Output Flip-Flop, IFF = Input Flip-Flop or Latch



XC4000E IOB Input Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Pin-to-pin timing parameters are derived from measuring external and internal test patterns and are guaranteed over worst-case operating conditions (supply voltage and junction temperature). Listed below are representative values for typical pin locations and normal clock loading. For more specific, more precise, and worst-case guaranteed data, reflecting the actual routing structure, use the values provided by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. Values apply to all XC4000E devices unless otherwise noted.

	Speed	d Grade	-	4	-	3	-	2	_	1	Units
Description	Symbol	Device	Min	Max	Min	Max	Min	Max	Min	Max	Units
Propagation Delays (TTL Inputs)						•	•				
Pad to I1, I2											
Pad to I1, I2 via transparent	T _{PID}	All devices		3.0		2.5		2.0		1.4	ns
latch, no delay											
with delay	T _{PLI}	All devices		4.8		3.6		3.6		2.8	ns
	T _{PDLI}	XC4003E		10.4		9.3		6.9		6.4	ns
		XC4005E		10.8		9.6		7.4		6.5	ns
		XC4006E		10.8		10.2		8.1		6.9	ns
		XC4008E		10.8		10.6		8.2		7.0	ns
		XC4010E		11.0		10.8		8.3		7.3	ns
		XC4013E		11.4		11.2		9.8		8.4	ns
		XC4020E		13.8		12.4		11.5		9.0	ns
		XC4025E		13.8		13.7		12.4		_	ns
Propagation Delays (CMOS Inputs)											
Pad to I1, I2	T _{PIDC}	All devices		5.5		4.1		3.7		1.9	ns
Pad to I1, I2 via transparent											
latch, no delay	T _{PLIC}	All devices		8.8		6.8		6.2		3.3	ns
with delay	T _{PDLIC}	XC4003E		16.5		12.4		11.0		6.9	ns
		XC4005E		16.5		13.2		11.9		7.0	ns
		XC4006E		16.8		13.4		12.1		7.4	ns
		XC4008E		17.3		13.8		12.4		7.4	ns
		XC4010E		17.5		14.0		12.6		7.8	ns
		XC4013E		18.0		14.4		13.0		9.0	ns
		XC4020E		20.8		15.6		14.0		9.5	ns
		XC4025E		20.8		15.6		14.0		_	ns
Propagation Delays											
Clock (IK) to I1, I2 (flip-flop)	T _{IKRI}	All devices		5.6		2.8		2.8		2.7	ns
Clock (IK) to I1, I2											
(latch enable, active Low)	T _{IKLI}	All devices		6.2		4.0		3.9		3.2	ns
Hold Times (Note 1)											
Pad to Clock (IK), no delay	T _{IKPI}	All devices	0		0		0		0		ns
with delay	T _{IKPID}	All devices	0		0		0		0		ns
Clock Enable (EC) to Clock (IK),											
no delay	T _{IKEC}	All devices	1.5		1.5		0.9		0		ns
with delay	TIKECD	All devices	0		0		0		0		ns

Note 1: Input pad setup and hold times are specified with respect to the internal clock (IK). For setup and hold times with respect to the clock input pin, see the pin-to-pin parameters in the Guaranteed Input and Output Parameters table.

Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.



XC4000E IOB Input Switching Characteristic Guidelines (Continued)

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

		Speed G	rade	-	4	-	3	-	2	-	1	Units
Description	on	Symbol	Device	Min	Max	Min	Max	Min	Max	Min	Max	Units
Setup Times (TTL	Inputs)		'		ı							
Pad to Clock (IK),	no delay	T _{PICK}	All devices	4.0		2.6		2.0		1.5		ns
	with delay	T _{PICKD}	XC4003E	10.9		8.2		6.0		4.8		ns
			XC4005E	10.9		8.7		6.1		5.1		ns
			XC4006E	10.9		9.2		6.2		5.8		ns
			XC4008E	11.1		9.6		6.3		5.8		ns
			XC4010E	11.3		9.8		6.4		6.0		ns
			XC4013E	11.8		10.2		7.9		7.6		ns
			XC4020E	14.0		11.4		9.4		8.2		ns
			XC4025E	14.0		11.4		10.0		_		ns
Setup Time (CMO	S Inputs)											
Pad to Clock (IK),	no delay	T _{PICKC}	All devices	6.0		3.3		2.4		2.4		ns
	with delay	T _{PICKDC}	XC4003E	12.0		8.8		6.9		5.3		ns
			XC4005E	12.0		9.7		8.0		5.6		ns
			XC4006E	12.3		9.9		8.1		6.3		ns
			XC4008E	12.8		10.3		8.2		6.3		ns
			XC4010E	13.0		10.5		8.3		6.5		ns
			XC4013E	13.5		10.9		10.0		7.9		ns
			XC4020E	16.0		12.1		12.1		8.1		ns
			XC4025E	16.0		12.1		12.1		_		ns
(TTL or CMOS)												
Clock Enable (EC)	to Clock											
(IK), no delay		T _{ECIK}	All devices	3.5		2.5		2.1		1.5		ns
with delay		T _{ECIKD}	XC4003E	10.4		8.1		4.3		4.3		ns
			XC4005E	10.4		8.5		5.6		5.0		ns
			XC4006E	10.4		9.1		6.7		6.0		ns
			XC4008E	10.4		9.5		6.9		6.0		ns
			XC4010E	10.7		9.7		7.1		6.5		ns
			XC4013E	11.1		10.1		9.0		8.0		ns
			XC4020E	14.0		11.3		10.6		9.0		ns
			XC4025E	14.0		11.3		11.0		_		ns
Global Set/Reset (•											
Delay from GSR ne		T _{RRI}			12.0		7.8		6.8		6.8	ns
through Q to I1,	, I2											
GSR width		T _{MRW}		13.0		11.5		11.5		10.0		ns
GSR inactive to firs		T _{MRI}										
Clock (IK) edge												

Note 1: Input pad setup and hold times are specified with respect to the internal clock (IK). For setup and hold times with respect to the clock input pin, see the pin-to-pin parameters in the Guaranteed Input and Output Parameters table.

Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

Note 3: Timing is based on the XC4005E. For other devices see the XACT timing calculator.



XC4000E IOB Output Switching Characteristic Guidelines

Testing of switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are derived from measuring internal test patterns. Listed below are representative values. For more specific, more precise, and worst-case guaranteed data, use the values reported by the static timing analyzer (TRCE in the Xilinx Development System) and back-annotated to the simulation net list. These path delays, provided as a guideline, have been extracted from the static timing analyzer report. All timing parameters assume worst-case operating conditions (supply voltage and junction temperature). Values apply to all XC4000E devices unless otherwise noted.

Speed (Speed Grade		4	-3		-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Units
Propagation Delays (TTL Output Levels)										
Clock (OK) to Pad, fast	T _{OKPOF}		7.5		6.5		4.5	3.0		ns
slew-rate limited	T _{OKPOS}		11.5		9.5		7.0	5.0		ns
Output (O) to Pad, fast	T _{OPF}		8.0		5.5		4.8	3.2		ns
slew-rate limited	T _{OPS}		12.0		8.5		7.3	5.2		ns
3-state to Pad hi-Z	T _{TSHZ}		5.0		4.2		3.8	3.0		ns
(slew-rate independent)										
3-state to Pad active										
and valid, fast	T _{TSONF}		9.7		8.1		7.3	6.8		ns
slew-rate limited	T _{TSONS}		13.7		11.1		9.8	8.8		ns
Propagation Delays (CMOS O	utput Levels)		'		!					
Clock (OK) to Pad, fast	T _{OKPOFC}		9.5		7.8		7.0		4.0	ns
slew-rate limited	T _{OKPOSC}		13.5		11.6		10.4		7.0	ns
Output (O) to Pad, fast	T _{OPFC}		10.0		9.7		8.7		4.0	ns
slew-rate limited	T _{OPSC}		14.0		13.4		12.1		6.0	ns
3-state to Pad hi-Z	T _{TSHZC}		5.2		4.3		3.9		3.9	ns
(slew-rate independent)										
3-state to Pad active										
and valid, fast	T _{TSONFC}		9.1		7.6		6.8		6.8	ns
slew-rate limited	T _{TSONSC}		13.1		11.4		10.2		8.8	ns

Note 1: Output timing is measured at pin threshold, with 50pF external capacitive loads (incl. test fixture). Slew-rate limited output rise/fall times are approximately two times longer than fast output rise/fall times. For the effect of capacitive loads on ground bounce, see the "Additional XC4000 Data" section of the Programmable Logic Data Book.

Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.



IOB Output Switching Characteristics Guidelines (Continued)

Speed Grade		-	4	-	3	-	2	-	1	Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Units
Setup and Hold										
Output (O) to clock (OK) setup time	T _{OOK}	5.0		4.6		3.8		2.3		ns
Output (O) to clock (OK) hold time	T _{OKO}	0		0		0		0		ns
Clock Enable (EC) to clock (OK) setup	T _{ECOK}	4.8		3.5		2.7		2.0		ns
Clock Enable (EC) to clock (OK) hold	T _{OKEC}	1.2		1.2		0.5		0		ns
Clock		'	'	!		'	•			
Clock High Clock Low	T _{CH} T _{CL}	4.5 4.5		4.0 4.0		4.0 4.0			3.0 3.0	ns ns
Global Set/Reset (Note 3)										
Delay from GSR net to Pad GSR width GSR inactive to first active clock (OK) edge	T _{RPO} T _{MRW} T _{MRO}	13.0	15.0	11.5	11.8	11.5	8.7		7.0	ns ns

Note 1: Output timing is measured at pin threshold, with 50pF external capacitive loads (incl. test fixture). Slew-rate limited output rise/fall times are approximately two times longer than fast output rise/fall times. For the effect of capacitive loads on ground bounce, see the "Additional XC4000 Data" section of the Programmable Logic Data Book.

Note 2: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

Note 3: Timing is based on the XC4005E. For other devices see the XACT timing calculator.



XC4000E Boundary Scan (JTAG) Switching Characteristic Guidelines

Testing of the switching parameters is modeled after testing methods specified by MIL-M-38510/605. All devices are 100% functionally tested. Internal timing parameters are not measured directly. They are derived from benchmark timing patterns that are taken at device introduction, prior to any process improvements. For more detailed, more precise, and more up-to-date information, use the values provided by the XACT timing calculator and used in the simulator. These values can be printed in tabular format by running LCA2XNF -S.

The following guidelines reflect worst-case values over the recommended operating conditions. They are expressed in units of nanoseconds and apply to all XC4000E devices unless otherwise noted.

Speed (Speed Grade		4	-	3	-2		-1		Units
Description	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Ullits
Setup Times										
Input (TDI) to clock (TCK)	T _{TDITCK}	30.0		30.0		30.0		20.0		ns
Input (TMS) to clock (TCK)	T _{TMSTCK}	15.0		15.0		15.0		10.0		ns
Hold Times										
Input (TDI) to clock (TCK)	T _{TCKTDI}	0		0		0		0		ns
Input (TMS) to clock (TCK)	T _{TCKTMS}	0		0		0		0		ns
Propagation Delay										
Clock (TCK) to Pad (TDO)	T _{TCKPO}		30.0		30.0		30.0		20.0	ns
Clock										
Clock (TCK) High	T _{TCKH}	5.0		5.0		5.0		4.0		ns
Clock (TCK) Low	T _{TCKL}	5.0		5.0		5.0		4.0		ns
Frequency	F _{MAX}		15.0		15.0		15.0		25.0	MHz

- Note 1: Input setup and hold times and clock-to-pad times are specified with respect to external signal pins.
- Note 2: Output timing is measured at pin threshold, with 50pF external capacitive loads (incl. test fixture). Slew-rate limited output rise/fall times are approximately two times longer than fast output rise/fall times. For the effect of capacitive loads on ground bounce, see the "Additional XC4000 Data" section of the Programmable Logic Data Book.
- Note 3: Voltage levels of unused pads, bonded or unbonded, must be valid logic levels. Each can be configured with the internal pull-up (default) or pull-down resistor, or configured as a driven output, or can be driven from an external source.

Revision Control

Version	Nature of Changes
3/30/98 (1.5)	As submitted for the 1999 data book
1/29/99 (1.5)	Updated Switching Characteristics Tables
5/14/99 (1.6)	Replaced Electrical Specification and pinout pages for E, EX, and XL families with separate updates and added URL link on placeholder page for electrical specifications/pinouts for WebLINX users
8/27/99 (1.7)	Included missing IOB Propagation Delay page (6-113)